

Robust Empirical Bayes Estimation of the Elliptically Countoured Covariance Matrix

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Abstract. Let \mathbf{S} be the matrix of residual sum of square in linear model $\mathbf{Y} = \mathbf{A}\boldsymbol{\beta} + \mathbf{e}$, where the matrix of errors is distributed as elliptically contoured with unknown scale matrix $\boldsymbol{\Sigma}$. For Stein loss function, $L_1(\hat{\boldsymbol{\Sigma}}, \boldsymbol{\Sigma}) = \text{tr}(\hat{\boldsymbol{\Sigma}}\boldsymbol{\Sigma}^{-1}) - \log |\hat{\boldsymbol{\Sigma}}\boldsymbol{\Sigma}^{-1}| - p$, and squared loss function, $L_2(\hat{\boldsymbol{\Sigma}}, \boldsymbol{\Sigma}) = \text{tr}(\hat{\boldsymbol{\Sigma}}\boldsymbol{\Sigma}^{-1} - \mathbf{I})^2$, we offer empirical Bayes estimators of $\boldsymbol{\Sigma}$, which dominate any scalar multiple of \mathbf{S} , i.e., $a\mathbf{S}$, by an effective amount. In fact, this study somehow shows that improvement of the empirical Bayes estimators obtained under the normality assumption remains robust under elliptically contoured model.

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1. Introduction

The problem of empirical Bayes (EB) estimation with the normal covariance matrix $\boldsymbol{\Sigma}$, was considered by [3], who proved that these estimators dominate all scalar multiples of the unbiased estimator. Our objective is to establish the dominance results by Haff [4] remains robust under the elliptically contoured distribution which we refer to it as ECD in this

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paper. Here, we consider the problem of estimation with the elliptically contoured covariance matrix Σ ; then we get the empirical Bayes estimators which dominate the usual unbiased estimators for each of two invariant loss functions L_1 and L_2 . The dominance results under L_1 and L_2 were first offered by James and Stein. There are many studies to estimate a covariance matrix for the normality assumption; under loss functions L_1 and L_2 , see [2,3], [6], [9] and [11], [8], [10]. The identity for the ECD which was derived by [7], known in the literature as the "Stein-Haff identity", is applied to compute risk functions.

Let \mathbf{Y} be an $N \times p$ random matrix with multivariate linear model

$$\mathbf{Y} = \mathbf{A}\boldsymbol{\beta} + \mathbf{e}$$

where \mathbf{e} is an $N \times p$ matrix of random errors, \mathbf{A} is a known full rank $N \times m$ matrix and $\boldsymbol{\beta}$ is an $m \times p$ matrix of unknown parameters. We assume that the error matrix \mathbf{e} has an elliptical density

$$|\Sigma|^{-\frac{N}{2}} f(\text{tr}(\Sigma^{-1} \mathbf{e}^t \mathbf{e}))$$

where Σ is a $p \times p$ unknown positive-definite matrix, $f(\cdot)$ is a differentiable and nonnegative real-value function. Here $|\mathbf{B}|$, $\text{tr}(\mathbf{B})$ and \mathbf{B}^t stand for the determinant, the trace and the transpose of a square matrix \mathbf{B} , respectively.

Let \mathbf{S} be the matrix of residual sum of squares, i.e.,

$$\mathbf{S} = \mathbf{Y}^t (\mathbf{I}_N - \mathbf{A}(\mathbf{A}^t \mathbf{A})^{-1} \mathbf{A}^t) \mathbf{Y},$$

and let $n = N - m$. Under the elliptically assumption, the expected value for various functions of \mathbf{S} have been derived; by [7].

Let $\hat{\Sigma}$ be an estimator of Σ . We assume that the loss function is

$$L_1(\hat{\Sigma}, \Sigma) = \text{tr}(\hat{\Sigma} \Sigma^{-1}) - \log |\hat{\Sigma} \Sigma^{-1}| - p,$$

or

$$L_2(\hat{\Sigma}, \Sigma) = \text{tr}(\hat{\Sigma} \Sigma^{-1} - \mathbf{I})^2,$$

and define the risk function by

$$R_i(\hat{\Sigma}, \Sigma) = E[L_i(\hat{\Sigma}, \Sigma)|\Sigma], \quad i = 1, 2.$$

Let $\hat{\Sigma}$ and $\hat{\Sigma}_*$ be the competing estimators of Σ , where $\hat{\Sigma}$ dominates $\hat{\Sigma}_*$ (mod L_i) if $R_i(\hat{\Sigma}, \Sigma) \leq R_i(\hat{\Sigma}_*, \Sigma) (\forall \Sigma)$.

According to the same notation used in [7], let $f^{(0)}(x) = f(x)$,

$$f^{(k+1)}(x) = \frac{1}{2} \int_x^\infty f^{(k)}(t) dt, \quad k = 0, 1$$

and

$$E_{\Sigma}^{(k)}[v(\mathbf{S})] = \int v(\mathbf{S}) |\Sigma|^{-\frac{N}{2}} f^{(k)} \left(\text{tr}(\Sigma^{-1}(\mathbf{y} - \mathbf{A}\beta)^t(\mathbf{y} - \mathbf{A}\beta)) \right) d\mathbf{y}$$

where $v(\mathbf{S})$ is an integrable function of \mathbf{S} . Also we use the transformation to polar coordinates to get,

$$E_{\Sigma}^{(k)}[1] = \gamma(k) = \frac{2\pi^{NP/2}}{\Gamma(NP/2)} \int_0^\infty r^{NP-1} f^{(k)}(r^2) dr, \quad k = 0, 1, 2 \quad (1)$$

and assume that $\gamma(i) < \infty$, for more details see [7].

Following [3], the empirical Bayes estimators have the form

$$\hat{\Sigma} = a[\mathbf{S} + ut(u)\mathbf{C}] \quad (2)$$

[5] where $t(\cdot)$ is a nonnegative and non-increasing function, \mathbf{C} is an arbitrary positive definite matrix, $u = (\text{tr}\mathbf{S}^{-1})^{-1}$ and

$$0 \leq a \leq \max\left\{\frac{1}{n\gamma(1)}, \frac{\gamma(1)}{(n+p+1)\gamma(2)}\right\}.$$

Without loss of generality, we assume $\mathbf{C} = \mathbf{I}$. It should be noted that for $t \equiv 0$, we have the obvious estimators, the scalar multiples of \mathbf{S} .

1.1 Synopsis

The consideration of the scalar multiples of \mathbf{S} shows that the best estimator (mod L_1) is the unbiased estimator

$$\hat{\Sigma}_1 = \frac{1}{n\gamma(1)} \mathbf{S}$$

and the best estimator (mod L_2) is

$$\hat{\Sigma}_2 = \frac{\gamma(1)}{(n+p+1)\gamma(2)} \mathbf{S}.$$

The main result of this paper deals with the EB estimators(2). Furthermore, for each loss function, there are conditions under which they dominate the best scalar multiple of \mathbf{S} .

1.2 Stein-Haff Identity and Its Application

Let $T(\mathbf{S}) = (t_{ij}(\mathbf{S}))$ be a $p \times p$ matrix whose elements are functions of $\mathbf{S} = (s_{ij})$. Denote

$$\{D_{\mathbf{S}}T(\mathbf{S})\}_{ij} = \sum_{a=1}^p \frac{1}{2}(1 + \delta_{ia}) \frac{\partial t_{aj}(\mathbf{S})}{\partial s_{ia}} \quad (3)$$

where δ_{ia} is Kronecker's delta. From Lemma 1 in [11], for suitable choice of a matrix $T(\mathbf{S})$, the Stein-Haff identity is given by

$$E_{\Sigma}^{(k)} \left[\text{tr}\{\Sigma^{-1}T(\mathbf{S})\} \right] = E_{\Sigma}^{(k+1)} \left[(n-p-1) \text{tr}\{\mathbf{S}^{-1}T(\mathbf{S})\} + 2 \text{tr}D_{\mathbf{S}}T(\mathbf{S}) \right] \quad (4)$$

and from (3) and (4) for a real valued function $h(\mathbf{S})$, we observe that

$$E_{\Sigma}^{(k)} \left[\text{tr}(\Sigma^{-1}h(\mathbf{S})) \right] = E_{\Sigma}^{(k+1)} \left[(n-p-1) h(\mathbf{S}) \text{tr}(\mathbf{S}^{-1}) + \text{tr}\left(\frac{\partial h(\mathbf{S})}{\partial \mathbf{S}}\right) \right] \quad (5)$$

First, we apply (4) and (5) to calculate risk function R_1 . It appears that $\alpha_1(\Sigma) = R_1(\hat{\Sigma}, \Sigma) - R_1(\hat{\Sigma}_1, \Sigma)$ has terms under the unusual expectation of the form $h(\mathbf{S})\text{tr}(\Sigma^{-1})$. Theorem 2.3 gives conditions under which $\alpha_1(\Sigma) \leq 0$ ($\forall \Sigma$). Since $\alpha_2(\Sigma) = R_2(\hat{\Sigma}, \Sigma) - R_2(\hat{\Sigma}_2, \Sigma)$ has terms which are quadratic in Σ^{-1} , calculating R_2 is more difficult than R_1 .

2. Main Results

The following four theorems are the main results of this paper. The proofs are postponed to Section 3.

Theorem 2.1. *Under the loss function L_1 , the best estimator of the form $\hat{\Sigma}_a = a\mathbf{S}$ is given by $a = \frac{1}{n\gamma(1)}$.*

Theorem 2.2. *Under the loss function L_2 , the best estimator of the form $\hat{\Sigma}_a = a\mathbf{S}$ is given by $a = \frac{\gamma(1)}{(n+p+1)\gamma(2)}$.*

Our main result concern the EB estimators (2). For comparing $\hat{\Sigma}$ with $\hat{\Sigma}_i, i = 1, 2$, a is replaced by $\frac{1}{n\gamma(1)}$ and $\frac{\gamma(1)}{(n+p+1)\gamma(2)}$.

Theorem 2.3. *Let $\hat{\Sigma}$ is given by (2), with*

- i) $a = \frac{1}{n\gamma(1)}$,
- ii) $u = (\text{tr} \mathbf{S}^{-1})^{-1}$
- iii) t is a constant, $0 \leq t \leq \frac{2(n\gamma(0)+p-n)}{n\gamma(0)}$.

*Then $\hat{\Sigma}$ dominates $\hat{\Sigma}_1$ (mod L_1), i.e., $R_1(\hat{\Sigma}, \Sigma) \leq R_1(\hat{\Sigma}_1, \Sigma)$ ($\forall \Sigma$).
An optimal value of t is $\frac{n\gamma(0)+p-n}{n\gamma(0)}$ (as seen from the proof).*

Theorem 2.4. *Let $\hat{\Sigma}$ is given by (2), with*

- i) $a = \frac{\gamma(1)}{(n+p+1)\gamma(2)}$,
- ii) $u = (\text{tr} \mathbf{S}^{-1})^{-1}$
- iii) t is a constant, $0 \leq t \leq \frac{2[(n-2p+1)-p(n-1)(n-p)]}{p(n-p-1)(n-p+1)}$.

Then $\hat{\Sigma}$ dominates $\hat{\Sigma}_2$ (mod L_2), i.e., $R_2(\hat{\Sigma}, \Sigma) \leq R_2(\hat{\Sigma}_2, \Sigma)$ ($\forall \Sigma$).

The choice $\frac{(n-2p+2)-p(n-1)(n-p)}{p(n-p-1)(n-p+1)}$ of t is the optimal choice.

The latter calculations depends on the following lemmas.

Lemma 2.5. [Hisayuki Tsukuma 2005] *Let \mathbf{Q} be a $p \times p$ matrix of constants. Under the conditions of Lemma 2.1. in [5](see appendix), we have*

- i) $E_{\Sigma}^{(0)}[\mathbf{S}] = n\gamma(1)\Sigma,$
- ii) $E_{\Sigma}^{(0)}[\mathbf{S}\mathbf{Q}\mathbf{S}] = \gamma(2)\{n^2\Sigma\mathbf{Q}\Sigma + n\Sigma\mathbf{Q}^t\Sigma + n\text{tr}(\mathbf{Q}\Sigma)\Sigma\}.$

Lemma 2.6. *Let \mathbf{F} be a $p \times p$ matrix-valued function of $\mathbf{S} = (s_{ij})$ and $\phi(\mathbf{S})$ be a scalar function of \mathbf{S} . Then, we have*

- i) $D_{\mathbf{S}}(\phi \mathbf{F}) = \frac{1}{2}(\frac{\partial \phi}{\partial \mathbf{S}} \cdot \mathbf{F}) + \phi D_{\mathbf{S}}\mathbf{F},$
- and for a matrix $\mathbf{Q}_{p \times p}$ of constants,
- ii) $D_{\mathbf{S}}(\mathbf{S}\mathbf{Q}) = (\mathbf{Q} + p \mathbf{Q}^t)/2,$
 - iii) $D_{\mathbf{S}}(\mathbf{S}^{-2} \mathbf{Q}) = -\mathbf{S}^{-3}\mathbf{Q} - \{\text{tr}(\mathbf{S}^{-1})\mathbf{S}^{-2}\mathbf{Q} + \text{tr}(\mathbf{S}^{-2})\mathbf{S}^{-1}\mathbf{Q}\}/2,$
 - iv) $D_{\mathbf{S}}(\mathbf{S}^{-1}\mathbf{Q}) = -\{\mathbf{S}^{-2}\mathbf{Q} + \text{tr}(\mathbf{S}^{-1})\mathbf{S}^{-1}\mathbf{Q}\}/2.$

Proof.(i) For a matrix $F(\mathbf{S})_{p \times p}$ and a scalar $\phi(\mathbf{S})$, from (3) we have

$$\begin{aligned}
 [D_{\mathbf{S}}\phi\mathbf{F}]_{ij} &= \sum_a \frac{1}{2}(1 + \delta_{ia}) \frac{\partial}{\partial s_{ia}} (\phi\mathbf{F})_{aj} \\
 &= \sum_a \frac{1}{2}(1 + \delta_{ia}) \left\{ \frac{\partial \phi}{\partial s_{ia}} (\mathbf{F})_{aj} + \frac{\partial (\mathbf{F})_{aj}}{\partial s_{ia}} \cdot \phi \right\} \\
 &= \sum_a \frac{1}{2}(1 + \delta_{ia}) \left(\frac{\partial \phi}{\partial \mathbf{S}} \right)_{ia} (\mathbf{F})_{aj} \\
 &\quad + \phi \sum_a \frac{1}{2}(1 + \delta_{ia}) \frac{\partial (\mathbf{F})_{aj}}{\partial s_{ia}} \\
 &= \frac{1}{2} \left(\frac{\partial \phi}{\partial \mathbf{S}} \cdot \mathbf{F} \right)_{ij} + \phi (D_{\mathbf{S}}\mathbf{F})_{ij}
 \end{aligned}$$

which gives Lemma 3.2 (i). \square

The following properties of the operator $D_{\mathbf{S}}$ (see the definition in (3)) are required for computations.

Proof.(ii) For a matrix Q of constant, to derive Lemma 3.2 (ii), we note that

$$\begin{aligned} [D_S S Q]_{ij} &= \frac{1}{2} \sum_a (1 + \delta_{ia}) \frac{\partial}{\partial s_{ia}} (S Q)_{aj} \\ &= \frac{1}{2} \sum_a \{ \delta_{ia} Q_{aj} + \delta_{aa} Q_{ij}^t \} \\ &= \frac{1}{2} (I Q)_{ij} + \frac{P}{2} Q_{ij}^t. \end{aligned}$$

Proof.(iii) Applying

$$\frac{\partial (S^{-1})_{kl}}{\partial s_{ij}} = \{ -(S^{-1})_{ki} (S^{-1})_{jl} - (S^{-1})_{li} (S^{-1})_{jk} \},$$

we obtain

$$\begin{aligned} [D_S S^{-2} Q]_{ij} &= \sum_{a,k} \frac{1}{2} (1 + \delta_{ia}) \frac{\partial}{\partial s_{ia}} \left[(S^{-1})_{ak} (S^{-1} Q)_{kj} \right] \\ &= -\frac{1}{2} \sum_{a,k} (S^{-1})_{ia} (S^{-1})_{ak} (S^{-1} Q)_{kj} \\ &\quad - \frac{1}{2} \left(\sum_k (S^{-1})_{ik} (S^{-1} Q)_{kj} \right) \left(\sum_a (S^{-1})_{aa} \right) \\ &\quad - \frac{1}{2} \left(\sum_{a,k} (S^{-1})_{ak} (S^{-1})_{ki} \right) \left(\sum_m (S^{-1})_{am} Q_{mj} \right) \\ &\quad - \frac{1}{2} \left(\sum_{a,k} (S^{-1})_{ak} (S^{-1})_{ak} \right) \left(\sum_m (S^{-1})_{mi} Q_{mj} \right) \\ &= -\frac{1}{2} (S^{-3} Q)_{ij} - \frac{1}{2} \text{tr}(S^{-1}) (S^{-2} Q)_{ij} - \frac{1}{2} (S^{-3} Q)_{ij} \\ &\quad - \frac{1}{2} \text{tr}(S^{-2}) (S^{-1} Q)_{ij}. \end{aligned}$$

(iv). This is given by the similar way in [4]. \square

Proof of Theorem 2.1. The proof is similar to that of Theorem 4.1. in [5]; therefore, we state the outline of the proof only. Let $\hat{\Sigma}_{1k} =$

$\frac{1}{n\gamma(1)}(1+k)\mathbf{S}$, $|k| < 1$ and $\hat{\Sigma}_1 = \frac{1}{n\gamma(1)}\mathbf{S}$. We want to show that

$$R_1(\hat{\Sigma}_{1k}, \Sigma) - R_1(\hat{\Sigma}_1, \Sigma) = E_{\Sigma}^{(0)} \left[\frac{k}{n\gamma(1)} \text{tr}(\mathbf{S}\Sigma^{-1}) - p \log(1+k) \right] \geq 0 \quad (\forall \Sigma). \quad (6)$$

From Lemma 2.5(i), we can see that

$$R_1(\hat{\Sigma}_{1k}, \Sigma) - R_1(\hat{\Sigma}_1, \Sigma) = pk - p \log(1+k).$$

Similar to [5], the inequality (6) holds and the proof is complete. \square

Proof of Theorem 2.2. The risk of a scalar multiple of \mathbf{S} is

$$\begin{aligned} R_2(a\mathbf{S}, \Sigma) &= E_{\Sigma}^{(0)} \text{tr}(a\mathbf{S}\Sigma^{-1} - \mathbf{I})^2 = \\ &= a^2 E_{\Sigma}^{(0)} \text{tr}(\mathbf{S}\Sigma^{-1}\mathbf{S}\Sigma^{-1}) - 2a E_{\Sigma}^{(0)} \text{tr}(\mathbf{S}\Sigma^{-1}) + p E_{\Sigma}^{(0)}[1]. \end{aligned}$$

Using (1) and Lemma 2.5 (i) and (ii), we have

$$R_2(a\mathbf{S}, \Sigma) = \gamma(2)a^2p(n^2 + n + np) - 2\gamma(1)nap + p\gamma(0)$$

and the last equality is minimized at $a = \frac{\gamma(1)}{(n+p+1)\gamma(2)}$. \square

Proof of Theorem 2.3. Write (2) as

$$\hat{\Sigma} = a\mathbf{S} + g(\mathbf{S})\mathbf{I} \quad (7)$$

where $g(\mathbf{S}) = \text{aut}(u)$. Taking differentiating of u with respect to \mathbf{S} gives

$$\frac{\partial u}{\partial \mathbf{S}} = -(\text{tr}\mathbf{S}^{-1})^{-2} \frac{\partial(\text{tr}\mathbf{S}^{-1})}{\partial \mathbf{S}} = u^2\mathbf{S}^{-2}.$$

As a result, we obtain

$$\frac{\partial g(\mathbf{S})}{\partial \mathbf{S}} = a \left[\frac{\partial u}{\partial \mathbf{S}} t(u) + u \frac{\partial t(u)}{\partial \mathbf{S}} \right] = a \left[u^2 t(u) + \frac{\partial t(u)}{\partial u} u^3 \right] \mathbf{S}^{-2}. \quad (8)$$

Let $t(u)$ be a constant function, the equation (8) implies that

$$\frac{\partial g(\mathbf{S})}{\partial \mathbf{S}} = au^2 t \mathbf{S}^{-2}. \quad (9)$$

From [5] we have the

$$\rho_k = \text{tr} \left(\frac{\mathbf{S}^{-1}}{\text{tr} \mathbf{S}^{-1}} \right)^k, \quad k = 1, 2, \dots \quad (10)$$

It is convenient to note that ρ_k decreases in k and $0 \leq \rho_k \leq 1$.

Use (7) with $a = \frac{1}{n\gamma(1)}$ and

$$\alpha_1 = R_1(\hat{\Sigma}, \Sigma) - R_1(\hat{\Sigma}_1, \Sigma) = E_{\Sigma}^{(0)} \left[g(\mathbf{S}) \text{tr} \Sigma^{-1} - \log |\mathbf{I} + n\gamma(1)g(\mathbf{S})\mathbf{S}^{-1}| \right].$$

Knowing that $t(u)$ is a constant, say t , and from (5) with $h = g$, and applying the expansion

$$\log |\mathbf{I} + \alpha \mathbf{B}| = \sum_{n=1}^{\infty} \frac{(-1)^{n-1}}{n} \alpha^n \text{tr}(\mathbf{B}^n)$$

where α is a real number and $\mathbf{B}_{p \times p}$ a symmetric matrix, we obtain

$$\alpha_1 = E_{\Sigma}^{(1)} \left[(n-p-1)g(\mathbf{S})\text{tr}(\mathbf{S}^{-1}) + \text{tr} \left(\frac{\partial g(\mathbf{S})}{\partial \mathbf{S}} \right) \right] - E_{\Sigma}^{(0)} \left[\sum_{i=1}^{\infty} \frac{(-1)^{i-1}}{i} t^i \rho_i \right]. \quad (11)$$

A simple calculation shows that

$$\sum_{i=1}^{\infty} \frac{(-1)^{i-1}}{i} t^i \rho_i \geq t - \frac{1}{2} t^2,$$

because the terms of the above series are in decreasing magnitude. Substituting (9) into (11), with $a = \frac{1}{n\gamma(1)}$, we obtain

$$\begin{aligned} \alpha_1 &\leq \frac{1}{n\gamma(1)} E_{\Sigma}^{(1)} \left[(n-p-1)t + \rho_2 t \right] + E_{\Sigma}^{(0)} \left[\frac{1}{2} t^2 - t \right], \\ &\leq \frac{1}{n\gamma(1)} (n-p)t E_{\Sigma}^{(1)} [1] + \left(\frac{1}{2} t^2 - t \right) E_{\Sigma}^{(0)} [1], \quad (\text{since } \rho_2 \leq 1), \\ &\leq \left[\frac{n-p}{n} - \gamma(0) \right] t + \frac{\gamma(0)}{2} t^2 \quad (\text{from (1)}). \end{aligned} \quad (12)$$

A sufficient condition for $\alpha_1(\mathbf{\Sigma}) \leq 0$ ($\forall \mathbf{\Sigma}$) is

$$\left[\frac{n-p}{n} - \gamma(0) \right] t + \frac{\gamma(0)}{2} t^2 \leq 0.$$

Finally, it is seen that

$$0 \leq t \leq \frac{2(n\gamma(0) + p - n)}{n\gamma(0)}$$

It is also seen, from (12) that (11) is bounded above by $\left[\frac{n-p}{n} - \gamma(0) \right] t + \frac{\gamma(0)}{2} t^2$; hence, the optimal t is $\frac{n\gamma(0) + p - n}{n\gamma(0)}$. \square

Theorem 2.4. compares $\hat{\mathbf{\Sigma}}$ in (7) and $\hat{\mathbf{\Sigma}}_2 = a\mathbf{S}$, $a = \frac{\gamma(1)}{(n+p+1)\gamma(2)}$. Let

$$\begin{aligned} \alpha_2(\mathbf{\Sigma}) &= R_2(\hat{\mathbf{\Sigma}}, \mathbf{\Sigma}) - R_2(\hat{\mathbf{\Sigma}}_2, \mathbf{\Sigma}) \\ &= E_{\mathbf{\Sigma}}^{(0)} \left[2a g(\mathbf{S}) \text{tr}(\mathbf{S}\mathbf{\Sigma}^{-2}) \right] - 2 g(\mathbf{S}) \text{tr}(\mathbf{\Sigma}^{-1}) + g^2(\mathbf{S}) \text{tr}(\mathbf{\Sigma}^{-2}) \end{aligned} \quad (13)$$

Then identities for the terms in (13) are given in the following Lemma.

Lemma 2.7. *Under conditions of Lemma 5.2.[5] (see appendix)*

i) For $h(\mathbf{S}) = 2a g(\mathbf{S})$, we have

$$\begin{aligned} E_{\mathbf{\Sigma}}^{(0)} [h(\mathbf{S}) \text{tr}(\mathbf{\Sigma}^{-2} \mathbf{S})] &= E_{\mathbf{\Sigma}}^{(2)} \left[n(n-p-1) h(\mathbf{S}) \text{tr}(\mathbf{S}^{-1}) \right. \\ &\quad \left. - (p+1) \text{tr} \left(\frac{\partial h(\mathbf{S})}{\partial \mathbf{S}} \right) \right. \\ &\quad \left. + 2 \text{tr} D_{\mathbf{S}} \left(\frac{\partial h(\mathbf{S})}{\partial \mathbf{S}} \cdot \mathbf{S} \right) \right] \end{aligned}$$

ii) For $h(\mathbf{S}) = -2g(\mathbf{S})$, we obtain

$$E_{\mathbf{\Sigma}}^{(0)} [h(\mathbf{S}) \text{tr}(\mathbf{\Sigma}^{-1})] = E_{\mathbf{\Sigma}}^{(1)} \left[(n-p-1) h(\mathbf{S}) \text{tr}(\mathbf{S}^{-1}) + \text{tr} \left(\frac{\partial h(\mathbf{S})}{\partial \mathbf{S}} \right) \right]$$

iii) For $h(\mathbf{S}) = g^2(\mathbf{S})$, we get

$$\begin{aligned} E_{\Sigma}^{(0)}[h(\mathbf{S}) \operatorname{tr}(\Sigma^{-2})] &= E_{\Sigma}^{(2)} \left[2 \operatorname{tr} D_{\mathbf{S}} \left(\frac{\partial h(\mathbf{S})}{\partial \mathbf{S}} \right) + 2(n-p-1) \right. \\ &\quad \left. \operatorname{tr}(\mathbf{S}^{-1} \frac{\partial h(\mathbf{S})}{\partial \mathbf{S}}) + (n-p-1) \right. \\ &\quad \left. (n-p-2)h(\mathbf{S}) \operatorname{tr}(\mathbf{S}^{-2}) \right. \\ &\quad \left. - (n-p-1)h(\mathbf{S}) \operatorname{tr}^2(\mathbf{S}^{-1}) \right] \end{aligned}$$

Proof (i). Set $\mathbf{T} = \mathbf{S}\Sigma^{-1}h(\mathbf{S})$, by using (4), we can see

$$\begin{aligned} E_{\Sigma}^{(0)} \left[\operatorname{tr}(\Sigma^{-1} \mathbf{S} \Sigma^{-1} h(\mathbf{S})) \right] &= \\ E_{\Sigma}^{(1)} \left[(n-p-1) \operatorname{tr}(h(\mathbf{S}) \Sigma^{-1}) + 2 \operatorname{tr} D_{\mathbf{S}}(h(\mathbf{S}) \mathbf{S} \Sigma^{-1}) \right]. \end{aligned}$$

Now applying Lemma 2.6 (i) and (ii) with $\mathbf{Q} = \Sigma^{-1}$ to the second term $D_{\mathbf{S}}(\mathbf{S}\Sigma^{-1}h(\mathbf{S}))$; hence, we get

$$E_{\Sigma}^{(0)} \left[h(\mathbf{S}) \operatorname{tr}(\Sigma^{-2} \mathbf{S}) \right] = E_{\Sigma}^{(1)} \left[n \operatorname{tr}(\Sigma^{-1} h(\mathbf{S})) + \operatorname{tr}(\Sigma^{-1} \frac{\partial h(\mathbf{S})}{\partial \mathbf{S}} \mathbf{S}) \right].$$

The result obtains by applying (5) to the first term and then (4) to the second.

(ii). In (5), set $k = 0$.

(iii). Put $\mathbf{T} = \Sigma^{-1}h(\mathbf{S})$. From (4) and Lemma 2.6. (i), we have

$$E_{\Sigma}^{(0)} \left[\operatorname{tr}(\Sigma^{-2} h(\mathbf{S})) \right] = E_{\Sigma}^{(1)} \left[(n-p-1) \operatorname{tr}(\Sigma^{-1} \mathbf{S}^{-1} h(\mathbf{S})) + \operatorname{tr}(\frac{\partial h(\mathbf{S})}{\partial \mathbf{S}} \Sigma^{-1}) \right].$$

Applying (4) to the first term with $\mathbf{T} = \mathbf{S}^{-1}h(\mathbf{S})$ and applying it to the second with $\mathbf{T} = \frac{\partial h(\mathbf{S})}{\partial \mathbf{S}}$, we obtain

$$\begin{aligned} E_{\Sigma}^{(0)} \left[\operatorname{tr}(\Sigma^{-2} h(\mathbf{S})) \right] &= E_{\Sigma}^{(2)} \left[(n-p-1)^2 h(\mathbf{S}) \operatorname{tr}(\mathbf{S}^{-2}) \right. \\ &\quad \left. + 2(n-p-1) \operatorname{tr} D_{\mathbf{S}}(\mathbf{S}^{-1} h(\mathbf{S})) \right. \\ &\quad \left. + (n-p-1) \operatorname{tr}(\mathbf{S}^{-1} \frac{\partial h(\mathbf{S})}{\partial \mathbf{S}}) \right. \\ &\quad \left. 2 \operatorname{tr} D_{\mathbf{S}}(\frac{\partial h(\mathbf{S})}{\partial \mathbf{S}}) \right]. \end{aligned}$$

Our result yields by using Lemma 2.6. (i) with $\mathbf{F} = \mathbf{S}^{-1}$ and $\phi = h$ and Lemma 2.6. (iv) with $\mathbf{Q} = \mathbf{I}$ to the second term.

The special of Lemma 2.7. by taking $g(\mathbf{S}) = aut$, $u = (\text{tr}(\mathbf{S}^{-1}))^{-1}$ and $a = \frac{\gamma(1)}{(n+p+1)\gamma(2)}$ is the following lemma. \square

Lemma 2.8. For $g(\mathbf{S}) = aut$,

- i) $E_{\Sigma}^{(0)} \left[2a^2 ut \text{tr}(\Sigma^{-2} \mathbf{S}) \right] = E_{\Sigma}^{(2)} \left[2na^2(n-p-1)t - 2a^2 \rho_2(p+2)t + 4a^2 t \rho_3 - 2a^2 t \right],$
- ii) $E_{\Sigma}^{(0)} \left[-2aut \text{tr}(\Sigma^{-1}) \right] = E_{\Sigma}^{(1)} \left[-2a(n-p-1)t - 2at \rho_2 \right],$
- iii) $E_{\Sigma}^{(0)} \left[a^2 u^2 t^2 \text{tr}(\Sigma^{-2}) \right] = E_{\Sigma}^{(2)} \left\{ -(n-p-1)a^2 t^2 + 6a^2 \rho_4 t^2 + 4a^2 t^2 \rho_3(n-p-2) + a^2 t \rho_2 [(n-p-1)^2 t - (n-p-1)t - 4t] \right\}$

Proof (i). In Lemma 2.7. (i), we put $h(\mathbf{S}) = 2a^2 ut$ and then compute $D_{\mathbf{S}}\left(\frac{\partial h(\mathbf{S})}{\partial \mathbf{S}} \cdot \mathbf{S}\right)$. By applying Lemma 2.6. (i), (iv) with $\phi = u^2$, $\mathbf{F} = \mathbf{S}^{-1}$ and $\mathbf{Q} = \mathbf{I}$, we have

$$\begin{aligned} \text{tr} D_{\mathbf{S}}\left(\frac{\partial h(\mathbf{S})}{\partial \mathbf{S}} \cdot \mathbf{S}\right) &= \text{tr} \left\{ 2a^2 t \left[\frac{1}{2} \frac{\partial u^2}{\partial \mathbf{S}} \mathbf{S}^{-1} + u^2 \left\{ -\frac{1}{2} \mathbf{S}^{-2} - \frac{1}{2} \text{tr}(\mathbf{S}^{-1}) \mathbf{S}^{-1} \right\} \right] \right\} \\ &= \text{tr} \left\{ 2a^2 t u^3 \mathbf{S}^{-3} - a^2 t u^2 \mathbf{S}^{-2} - a^2 t u^2 \text{tr}(\mathbf{S}^{-1}) \mathbf{S}^{-1} \right\} \\ &= 2a^2 t \rho_3 - a^2 t \rho_2 - a^2 t, \end{aligned}$$

Result (i) is now obtainable by using (9).

(ii). Using (9) and (10), the result obtains from Lemma 2.7. (ii) with $h(\mathbf{S}) = -2aut$.

(iii). Take $h(\mathbf{S}) = a^2 u^2 t^2$ in Lemma 2.7. (iii); then compute $D_{\mathbf{S}}\left(\frac{\partial h(\mathbf{S})}{\partial \mathbf{S}}\right)$. Similarly, using Lemma 2.6. (i), (iii) with $\phi = u^3$, $\mathbf{F} = \mathbf{S}^{-2}$

and $\mathbf{Q} = \mathbf{I}$, we have

$$\begin{aligned} \text{tr} D_{\mathbf{S}} \left(\frac{\partial h(\mathbf{S})}{\partial \mathbf{S}} \right) &= 2a^2 t^2 \text{tr} \left[\frac{1}{2} \left(\frac{\partial u^3}{\partial \mathbf{S}} \mathbf{S}^{-2} \right) + u^3 D_{\mathbf{S}} \mathbf{S}^{-2} \right] \\ &= a^2 t^2 [3\rho_4 - 2\rho_3 - 2\rho_2]. \end{aligned} \quad (14)$$

Now substitute (14) in Lemma 2.7. (iii) to achieve the result. \square

Proof of Theorem 2.4. Each term in (13) obtained from Lemma 2.7 (i), (ii) and (iii); hence, we have

$$\begin{aligned} \alpha_2 &= E_{\Sigma}^{(2)} \left[a^2 t \{ 2n(n-p-1) + 2\rho_2(p+2) + 4\rho_3 - 2 \} \right. \\ &\quad \left. + a^2 t^2 \{ -(n-p-1) + 6\rho_4 + 4\rho_3(n-p-2) + \rho_2(n-p-1)^2 \right. \\ &\quad \left. - \rho_2(n-p-1) - 4\rho_2 \} \right] + E_{\Sigma}^{(1)} \left[at \{ -2(n-p-1) - 2\rho_2 \} \right]. \end{aligned} \quad (15)$$

The above coefficient of $a^2 t$ can be written as $2[n(n-p-1) - 1] + 2\rho_2(p+2) + 4\rho_3$. Since $\rho_k \leq 1$ thus, the entire quantity is bounded above by

$$2[n(n-p-1) - 1] + 2(p+2) + 4 = 2[(n-1)(n-p) + 3]. \quad (16)$$

Since $\rho_k \searrow$, $0 \leq \rho_k \leq 1$ and $n > p+1$, the coefficient of $a^2 t^2$ is bounded above by

$$\rho_2 [2(n-p-1) + (n-p-1)^2 - 2]$$

and the above term is bounded by

$$\rho_2 [2(n-p-1) + (n-p-1)^2].$$

The above coefficient of ρ_2 is positive and $\rho_2 \leq 1$; accordingly, the coefficient of $a^2 t^2$ is bounded above by

$$(n-p-1)(n-p+1). \quad (17)$$

From [1], paper 137, we have $\frac{1}{p} \leq \rho_2 \leq 1$ then in (15), for the coefficient of at we can see

$$-2(n-p-1) - 2\rho_2 \leq -\frac{2}{p}. \quad (18)$$

Finally, from (15)-(18) a sufficient condition for $\alpha_2(\Sigma) \leq 0$ ($\forall \Sigma$) is

$$2a^2t[(n-1)(n-p)+3]\gamma(2)+a^2t^2(n-p-1)(n-p+1)\gamma(2)+at(-\frac{2}{p})\gamma(1) \leq 0. \quad (19)$$

Recall that $a = \frac{\gamma(1)}{\gamma(2)(n+p+1)}$ then (19) is equivalent to

$$0 \leq t \leq \frac{2[(n-2p+1)-p(n-1)(n-p)]}{p(n-p-1)(n-p+1)}.$$

The left hand side of (19) is minimized at $t = \frac{(n-2p+1)-p(n-1)(n-p)}{p(n-p-1)(n-p+1)}$. \square

Appendix

Lemma 2.1. *Let \mathbf{Q} be a $p \times p$ matrix of constants. If*

$$\lim_{z \rightarrow \pm\infty} |z|f^{(1)}(z^2 + a^2) = 0$$

for any real a , then we have

$$(i) \mathbb{E}_{\Sigma}^{(0)}[\mathbf{S}] = n\gamma(1)\Sigma.$$

If $\lim_{z \rightarrow \pm\infty} |z|^3 f^{(1)}(z^2 + a^2) = 0$ and $\lim_{z \rightarrow \pm\infty} |z|f^{(2)}(z^2 + a^2) = 0$

for any real a , then we have

$$(ii) \mathbb{E}_{\Sigma}^{(0)}[\mathbf{S}\mathbf{Q}\mathbf{S}] = \gamma(2)(n^2\Sigma\mathbf{Q}\Sigma + n\Sigma\dot{\mathbf{Q}}\Sigma + ntr(\mathbf{Q}\Sigma)\Sigma),$$

$$(iii) \mathbb{E}_{\Sigma}^{(0)}[tr(\mathbf{Q}\mathbf{S})\mathbf{S}] = \gamma(2)(n^2tr(\mathbf{Q}\Sigma)\Sigma + n\Sigma\mathbf{Q}\Sigma + n\Sigma\dot{\mathbf{Q}}\Sigma).$$

Lemma 5.2. *Let $\mathbf{G}(\mathbf{S}) = (g_{ab}(\mathbf{S})) = \mathbf{G}(\sum_{\mathbf{c}=1}^n \dot{\mathbf{z}}_{\mathbf{c}}\mathbf{z}_{\mathbf{c}})$, be a $p \times p$ matrix whose elements are differentiable with respect to z_{jk} ($j = 1, 2, \dots, n, k = 1, 2, \dots, p$). For $-2 \leq i \leq 1$, assume that*

$$(a) \mathbb{E}_{\Sigma}^i[|g_{ab}(\mathbf{S})|] < \infty;$$

$$(b) \lim_{z_{jk} \rightarrow \pm\infty} |z_{jk}| \mathbf{G}(\sum_{\mathbf{c}=1}^n \dot{\mathbf{z}}_{\mathbf{c}}\mathbf{z}_{\mathbf{c}})(\sum_{\mathbf{c}=1}^n \dot{\mathbf{z}}_{\mathbf{c}}\mathbf{z}_{\mathbf{c}})^{-1} f^{i+1}(z_{jk}^2 + a^2) = \mathbf{0}_{p \times p}$$

for any real a .

Then we have

$$\mathbb{E}_{\Sigma}^{(i)}[\Sigma^{-1}\mathbf{G}(\mathbf{S})] = \mathbb{E}_{\Sigma}^{(i+1)}[(n-p-1)\Sigma^{-1}\mathbf{G}(\mathbf{S}) + 2\mathbf{D}_s\mathbf{G}(\mathbf{S})].$$

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