Journal of Mathematical Extension Vol. 5, No. 2 (1), (2011), 23-29

Semismooth Function on Riemannian Manifolds

E. Ghahraei

University of Isfahan

Abstract. In this paper, We extend the concept of semismoothness for functions to the Riemannian manifolds setting. Then, some properties of these functions are studied.

AMS Subject Classification: 49J52; 58E30.

Keywords and Phrases: Semismoothness, Riemannian manifolds, locally lipschitz function.

1. Introduction

Semismoothness was originally introduced by Mifflin (see[3]) for functional. For function $F : \mathbb{R}^n \longrightarrow \mathbb{R}^n$, the concept of semismoothness is equivalent to the uniform convergence of directional derivatives in all directions.

Let $F : \mathbb{R}^n \longrightarrow \mathbb{R}^m$ be locally Lipschitz and D_F denote the set where F is differentiable. Then the Clark generalized Jacobian of F at x denoted by $\partial_{cl}F(x)$ is defined as

$$\partial_{cl}F(x) := co\{\lim_{x_n \longrightarrow x} JF(x_n) \mid x_n \longrightarrow x, x_n \in D_F\},\$$

where "J" denotes Jacobian and "co" stands for convex hull.

Definition 1.1. We say that a locally Lipschitz function $F : \mathbb{R}^n \longrightarrow \mathbb{R}^m$ is semismooth at x if

$$\lim_{v \in \partial_{cl} F(x+th'), \ h' \longrightarrow h, \ t \downarrow 0^+} vh', \tag{1}$$

Received November 2010; Final Revised January 2011

²³

exists for any $h \in \mathbb{R}^n$.

Convex functions, smooth functions and maximums of smooth functions are semismooth. Smooth compositions of semismooth functions are still semismooth. It was shown that a function F from \mathbb{R}^n to \mathbb{R}^m is semismooth if and only if all its components are semismooth. The proof of the following theorems can be found in [6].

Theorem 1.2. If F is semismooth, then the directional derivative

$$F'(x;h) = \lim_{t \to 0^+} \frac{1}{t} [F(x+th) - F(x)],$$

for $h \in \mathbb{R}^n$ exists and is equal to (2.1), i.e.

$$F'(x;h) = \lim_{v \in \partial_{cl} F(x+th'), \ h' \longrightarrow h, \ t \downarrow 0^+} vh',$$

for $h \in \mathbb{R}^n$.

Lemma 1.3. Suppose that $F : \mathbb{R}^n \longrightarrow \mathbb{R}^m$ is a locally Lipschitz function and F'(x;h) exists for each h at x. Then

(i) F'(x; .) is Lipschitz. (ii) for each h, there exists a $v \in \partial_{cl}F(x)$ such that

$$F'(x;h) = vh.$$

In the following, we introduce some fundamental properties and notations of Riemannian manifolds.

Definition 1.4. A real-valued function f defined on a complete Riemannian manifold M is said to be a convex if f is convex when restricted to any geodesics of M, which means that

$$(fo\gamma)(ta + (1-t)b) \leq tf(\gamma(a)) + (1-t)f(\gamma(b)),$$

holds for any $a, b \in \mathbb{R}$ and $0 \leq t \leq 1$.

Definition 1.5. A real-valued function f defined on a complete Riemannian manifold M is said to be Lipschitz if there exists a constant $L(M) = L \ge 0$ such that

$$|f(p) - f(q)| \leqslant Ld(p,q), \tag{2}$$

for all $p, p' \in M$, where d is the Riemannian distance on M. Besides this global concept, if for each $p_0 \in M$, there exists $L(p_0) \ge 0$ and $\delta = \delta(p_0) > 0$ such that Inequality (2.2) occurs with $L = L(p_0)$, for all $p, q \in B_{\delta}(p_0) := \{p \in M \mid d(p_0, p) < \delta\}$, then f is called locally Lipschitz.

Definition 1.6. Let M be a complete Riemannian manifold and let $f: M \longrightarrow \mathbb{R}$ be a convex function. Then the directional derivative of f at p in the direction $v \in T_pM$ is defined by

$$f'(p,v) = \lim_{t \longrightarrow 0^+} q_{\gamma_v}(t) = \inf_{t > 0} q_{\gamma_v}(t),$$

where $\gamma_v : \mathbb{R} \longrightarrow M$ is the geodesic such that $\gamma_v(0) = p, \gamma'_v(0) = v$ and

$$q_{\gamma}(t) = \frac{f(\gamma(t)) - f(p)}{t}.$$

Definition 1.7. Let $f: M \longrightarrow \mathbb{R}$ be a locally Lipschitz function and (U, φ) be a chart around $p \in M$. Then the clarke generalized Jacobian of f at p in the direction of $v \in T_pM$ is defined by

$$f^{0}(p,v) = \limsup_{t \downarrow 0, y \longrightarrow x} \frac{f o \varphi^{-1}(y+tv) - f o \varphi^{-1}(y)}{t},$$

where $\varphi(p) = x$. (see [2])

2. Semismoothness on Riemannian Manifolds

Definition 2.1. We say that a locally Lipschitz function $f : M \longrightarrow \mathbb{R}$ is semismooth at p, If there exists a chart (U, φ) at p such that $f \circ \varphi^{-1} : \mathbb{R}^n \longrightarrow \mathbb{R}$ is semismooth at $\varphi(p) = x \in \mathbb{R}^n$. It means that

$$\lim_{v \in \partial_{cl}(f \circ \varphi^{-1})(x+th), t \downarrow 0^+} vh, \tag{3}$$

exists for all $h \in \mathbb{R}^n$.

Note that by using a normal chart (U, φ) at p, the formula (3) gives us

$$\lim_{v \in \partial_{cl} f(\exp_p th), t \downarrow 0^+} vh, \tag{4}$$

for all $h \in T_p M \cong \mathbb{R}^n$.

In particular, observe that if $M = \mathbb{R}^n$, (4) implies (3).

Proposition 2.2. The above definition does not depend on the coordinate system.

Proof. Suppose that f is semismooth at p i.e. there exists a chart (U, φ) at p such that $f \circ \varphi^{-1}$ is semismooth at $\varphi(p)$. Now if there exists another chart such as (v, ψ) at p, we shall show that f in this chart is also semismooth, i.e. $f \circ \psi^{-1}$ at $\psi(p)$ is semismooth. We consider

$$fo\psi^{-1} = fo\varphi^{-1}o\varphi o\psi^{-1},$$

by assumption $f o \varphi^{-1}$ is semismooth and according to the C^{∞} structure on M, the combination $\varphi o \psi^{-1}$ is smooth and according to the properties of the resulting semismooth functions (see [4]), this combination is semismooth. Hence f is also semismooth in this chart and therefore the concept of semismoothness on manifolds does not depend on the coordinate system. \Box **Theorem 2.3.** Suppose that $f: M \longrightarrow \mathbb{R}$ is semismooth, then the directional derivative

$$f'(p;h) = \lim_{t \to 0^+} \frac{f(\gamma(t)) - f(p)}{t},$$

exists and is equal to

$$f'(p;h) = \lim_{v \in \partial_{cl} f(\exp_p th), t \downarrow 0} vh.$$

where $\gamma : \mathbb{R} \longrightarrow M$ is geodesic and $\gamma(0) = p, \gamma'(0) = h$.

Proof. Since $f: M \longrightarrow \mathbb{R}$ is semismooth, there is chart (U, φ) at p such that $f \circ \varphi^{-1} : \mathbb{R}^n \longrightarrow \mathbb{R}$ at $\varphi(p) = x \in \mathbb{R}^n$ is semismooth, As a result of theorem (2.2), the directional derivative

$$(fo\varphi^{-1})'(x;h) = \lim_{t \to 0} \frac{1}{t} [fo\varphi^{-1}(x+th) - fo\varphi^{-1}(x)],$$

exists and is equal to

$$(fo\varphi^{-1})'(x;h) = \lim_{v \in \partial_{cl}(fo\varphi^{-1})(x+th), t \downarrow 0} vh.$$
(5)

Left side of the above equality with respect to the normal coordinate system and property of exponential function $(\gamma_h(t) = \exp(th))$, can be written as follows

$$\lim_{t \to 0^+} \frac{f o \varphi^{-1}(x+th) - f o \varphi^{-1}(x)}{t} = \lim_{t \to 0^+} \frac{f(\gamma_h(t)) - f(p)}{t} = f'(p;h),$$
(6)

and also consider the right side of (5) as follows

$$\lim_{v \in \partial_{cl}(f \circ \varphi^{-1})(x+th), t \downarrow 0} vh = \lim_{v \in \partial_{cl}(f(\gamma_h(t)), t \downarrow 0} vh.$$
(7)

As a result of the (5), (6) and (7), one has that

$$f'(p;h) = \lim_{v \in \partial_{cl} f(\exp_p th), t \downarrow 0} vh.$$

This completes the proof. \Box

Theorem 2.4. Suppose that $f: M \longrightarrow \mathbb{R}$ is convex in the neighborhood of $p \in M$. Then f is semismooth at p.

Proof. For every sequence $\{p_k\}$ converges to $p(p_k \neq p)$ and for every sequence $\{v_k\}, v_k \in \partial_{cl} f(p_k)$, we have

$$\lim_{k \to \infty} f'(p; d_k) = \lim_{k \to \infty} (v_k)^T d_k,$$
(8)

where

$$d_k \equiv \frac{\exp_{p_k}^{-1} p}{\|\exp_{p_k}^{-1} p\|_{p_k}}.$$

Without loss of generality, can assume

 $\lim_{k \to \infty} d_k = d, \qquad \lim_{k \to \infty} v_k = v \in \partial_{cl} f(p).$ Since the left and the right limit of (8) are equal respectively with f'(p; d)and $v^T d$, Then

$$v^T d = f'(p; d)$$

Since f is convex and $v_k \in \partial_{cl} f(p_k)$, we have

$$f(p) - f(p_k) \ge \langle v_k, \exp_{p_k}^{-1} p \rangle,$$

and consider $k \longrightarrow \infty$,

$$v^T d \ge f'(p;d),$$

and since $v \in \partial_{cl} f(p)$, therefore, we have

$$f'(p;d) \ge v^T d.$$

Thus equality is established and the proof is completed. \Box

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Elham Ghahraei

Department of Mathematics Ph.D Student of Mathematics University of Isfahan Isfahan, Iran E-mail: ghahraeiel@yahoo.com