Semismooth Function on Riemannian Manifolds

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Abstract. In this paper, We extend the concept of semismoothness for functions to the Riemannian manifolds setting. Then, some properties of these functions are studied.

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1. Introduction

Semismoothness was originally introduced by Mifflin (see[3]) for functional. For function $F: \mathbb{R}^n \longrightarrow \mathbb{R}^n$, the concept of semismoothness is equivalent to the uniform convergence of directional derivatives in all directions.

Let $F: \mathbb{R}^n \longrightarrow \mathbb{R}^m$ be locally Lipschitz and D_F denote the set where F is differentiable. Then the Clark generalized Jacobian of F at x denoted by $\partial_{cl}F(x)$ is defined as

$$\partial_{cl}F(x) := co\{\lim_{x_n \longrightarrow x} JF(x_n) \mid x_n \longrightarrow x, x_n \in D_F\},$$

where "J" denotes Jacobian and "co" stands for convex hull.

Definition 1.1. We say that a locally Lipschitz function $F : \mathbb{R}^n \longrightarrow \mathbb{R}^m$ is semismooth at x if

$$\lim_{v \in \partial_{cl} F(x+th'), \ h' \longrightarrow h, \ t \downarrow 0^+} vh', \tag{1}$$

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exists for any $h \in \mathbb{R}^n$.

Convex functions, smooth functions and maximums of smooth functions are semismooth. Smooth compositions of semismooth functions are still semismooth. It was shown that a function F from \mathbb{R}^n to \mathbb{R}^m is semismooth if and only if all its components are semismooth. The proof of the following theorems can be found in [6].

Theorem 1.2. If F is semismooth, then the directional derivative

$$F'(x;h) = \lim_{t \to 0^+} \frac{1}{t} [F(x+th) - F(x)],$$

for $h \in \mathbb{R}^n$ exists and is equal to (2.1), i.e,

$$F'(x;h) = \lim_{v \in \partial_{cl} F(x+th'), h' \longrightarrow h, t \downarrow 0^+} vh',$$

for $h \in \mathbb{R}^n$.

Lemma 1.3. Suppose that $F: \mathbb{R}^n \longrightarrow \mathbb{R}^m$ is a locally Lipschitz function and F'(x;h) exists for each h at x. Then

- (i) F'(x; .) is Lipschitz.
- (ii) for each h, there exists a $v \in \partial_{cl} F(x)$ such that

$$F'(x;h) = vh.$$

In the following, we introduce some fundamental properties and notations of Riemannian manifolds.

Definition 1.4. A real-valued function f defined on a complete Riemannian manifold M is said to be a convex if f is convex when restricted to any geodesics of M, which means that

$$(fo\gamma)(ta + (1-t)b) \leqslant tf(\gamma(a)) + (1-t)f(\gamma(b)),$$

holds for any $a, b \in \mathbb{R}$ and $0 \le t \le 1$.

Definition 1.5. A real-valued function f defined on a complete Riemannian manifold M is said to be Lipschitz if there exists a constant $L(M) = L \geqslant 0$ such that

$$|f(p) - f(q)| \leqslant Ld(p, q), \tag{2}$$

for all $p, p' \in M$, where d is the Riemannian distance on M. Besides this global concept, if for each $p_0 \in M$, there exists $L(p_0) \geqslant 0$ and $\delta = \delta(p_0) > 0$ such that Inequality (2.2) occurs with $L = L(p_0)$, for all $p, q \in B_{\delta}(p_0) := \{p \in M \mid d(p_0, p) < \delta\}$, then f is called locally Lipschitz.

Definition 1.6. Let M be a complete Riemannian manifold and let $f: M \longrightarrow \mathbb{R}$ be a convex function. Then the directional derivative of f at p in the direction $v \in T_pM$ is defined by

$$f'(p,v) = \lim_{t \to 0^+} q_{\gamma_v}(t) = \inf_{t>0} q_{\gamma_v}(t),$$

where $\gamma_v : \mathbb{R} \longrightarrow M$ is the geodesic such that $\gamma_v(0) = p, \gamma_v'(0) = v$ and

$$q_{\gamma}(t) = \frac{f(\gamma(t)) - f(p)}{t}.$$

Definition 1.7. Let $f: M \longrightarrow \mathbb{R}$ be a locally Lipschitz function and (U, φ) be a chart around $p \in M$. Then the clarke generalized Jacobian of f at p in the direction of $v \in T_pM$ is defined by

$$f^{0}(p,v) = \limsup_{t \downarrow 0, y \longrightarrow x} \frac{f \circ \varphi^{-1}(y + tv) - f \circ \varphi^{-1}(y)}{t},$$

where $\varphi(p) = x$. (see [2])

2. Semismoothness on Riemannian Manifolds

Definition 2.1. We say that a locally Lipschitz function $f: M \longrightarrow \mathbb{R}$ is semismooth at p, If there exists a chart (U, φ) at p such that $f \circ \varphi^{-1} : \mathbb{R}^n \longrightarrow \mathbb{R}$ is semismooth at $\varphi(p) = x \in \mathbb{R}^n$. It means that

$$\lim_{v \in \partial_{cl}(f \circ \varphi^{-1})(x+th), t \downarrow 0^+} vh, \tag{3}$$

exists for all $h \in \mathbb{R}^n$.

Note that by using a normal chart (U, φ) at p, the formula (3) gives us

$$\lim_{v \in \partial_{cl} f(\exp_v th), t \downarrow 0^+} vh, \tag{4}$$

for all $h \in T_pM \cong \mathbb{R}^n$.

In particular, observe that if $M = \mathbb{R}^n$, (4) implies (3).

Proposition 2.2. The above definition does not depend on the coordinate system.

Proof. Suppose that f is semismooth at p i.e. there exists a chart (U,φ) at p such that $fo\varphi^{-1}$ is semismooth at $\varphi(p)$. Now if there exists another chart such as (v,ψ) at p, we shall show that f in this chart is also semismooth, i.e. $fo\psi^{-1}$ at $\psi(p)$ is semismooth. We consider

$$fo\psi^{-1} = fo\varphi^{-1}o\varphi o\psi^{-1},$$

by assumption $f \circ \varphi^{-1}$ is semismooth and according to the C^{∞} structure on M, the combination $\varphi \circ \psi^{-1}$ is smooth and according to the properties of the resulting semismooth functions (see [4]), this combination is semismooth. Hence f is also semismooth in this chart and therefore the concept of semismoothness on manifolds does not depend on the coordinate system. \square

Theorem 2.3. Suppose that $f: M \longrightarrow \mathbb{R}$ is semismooth, then the directional derivative

$$f'(p;h) = \lim_{t \longrightarrow 0^+} \frac{f(\gamma(t)) - f(p)}{t},$$

exists and is equal to

$$f'(p;h) = \lim_{v \in \partial_{cl} f(\exp_p th), t \downarrow 0} vh.$$

where $\gamma: \mathbb{R} \longrightarrow M$ is geodesic and $\gamma(0) = p, \gamma'(0) = h$.

Proof. Since $f: M \longrightarrow \mathbb{R}$ is semismooth, there is chart (U, φ) at p such that $f \circ \varphi^{-1} : \mathbb{R}^n \longrightarrow \mathbb{R}$ at $\varphi(p) = x \in \mathbb{R}^n$ is semismooth, As a result of theorem (2.2), the directional derivative

$$(f \circ \varphi^{-1})'(x; h) = \lim_{t \to 0} \frac{1}{t} [f \circ \varphi^{-1}(x + th) - f \circ \varphi^{-1}(x)],$$

exists and is equal to

$$(f \circ \varphi^{-1})'(x; h) = \lim_{v \in \partial_{cl}(f \circ \varphi^{-1})(x+th), t \downarrow 0} vh.$$
 (5)

Left side of the above equality with respect to the normal coordinate system and property of exponential function $(\gamma_h(t) = \exp(th))$, can be written as follows

$$\lim_{t \to 0^{+}} \frac{f \circ \varphi^{-1}(x+th) - f \circ \varphi^{-1}(x)}{t} = \lim_{t \to 0^{+}} \frac{f(\gamma_{h}(t)) - f(p)}{t} = f'(p;h),$$
(6)

and also consider the right side of (5) as follows

$$\lim_{v \in \partial_{cl}(f \circ \varphi^{-1})(x+th), t \downarrow 0} vh = \lim_{v \in \partial_{cl}(f(\gamma_h(t)), t \downarrow 0} vh. \tag{7}$$

As a result of the (5), (6) and (7), one has that

$$f'(p;h) = \lim_{v \in \partial_{cl} f(\exp_n th), t \downarrow 0} vh.$$

This completes the proof. \Box

Theorem 2.4. Suppose that $f: M \longrightarrow \mathbb{R}$ is convex in the neighborhood of $p \in M$. Then f is semismooth at p.

Proof. For every sequence $\{p_k\}$ converges to $p(p_k \neq p)$ and for every sequence $\{v_k\}, v_k \in \partial_{cl} f(p_k)$, we have

$$\lim_{k \to \infty} f'(p; d_k) = \lim_{k \to \infty} (v_k)^T d_k, \tag{8}$$

where

$$d_k \equiv \frac{\exp_{p_k}^{-1} p}{\| \exp_{p_k}^{-1} p \|_{p_k}}.$$

Without loss of generality, can assume

$$\lim_{k \to \infty} d_k = d, \qquad \lim_{k \to \infty} v_k = v \in \partial_{cl} f(p).$$

 $\lim_{k \longrightarrow \infty} d_k = d, \qquad \lim_{k \longrightarrow \infty} v_k = v \in \partial_{cl} f(p).$ Since the left and the right limit of (8) are equal respectively with f'(p;d)and $v^T d$, Then

$$v^T d = f'(p; d).$$

Since f is convex and $v_k \in \partial_{cl} f(p_k)$, we have

$$f(p) - f(p_k) \geqslant \langle v_k, \exp_{p_k}^{-1} p \rangle,$$

and consider $k \longrightarrow \infty$,

$$v^T d \geqslant f'(p; d),$$

and since $v \in \partial_{cl} f(p)$, therefore, we have

$$f'(p;d) \geqslant v^T d.$$

Thus equality is established and the proof is completed. \square

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