

Chemostat Model Analysis with Different Kernels and Fractional Derivatives

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Abstract

Three ordinary differential equations are used to represent mathematically the breakdown of a phenol and p-cresol combination in a constantly agitated bioreactor. The research offers a stability analysis of the model's equilibrium locations. Three different kernels have also been used to examine the effects of the fractal dimension and the fractional order on the model with the fractal-fractional derivatives. We have developed extremely effective computational techniques for phenol, p-cresol, and biomass concentrations. Finally, computer simulations are used to confirm the correctness of the suggested strategy.

Keywords: Bioreactor Model; Computational Methods, Fractal-Fractional Derivatives, Computational Simulations.

1. Introduction

There are numerous scientific articles that describe the discovery and work of microbial species that have greater chemical compound degradation activity [1]. Numerous individual microorganisms have been studied in [2]. The nature of the particular mixture and the used microbes determine whether one or all chemical components will biodegrade [3, 4, 5, 6]. The classical derivatives have a significant extension in fractional calculus. Fractional differential equations (FDEs) have recently been used in a variety of disciplines. Many authors have worked on these equations such as KdV equation [7], advection-dispersion equation [8], telegraph equation [9], Schrodinger equation [10], heat equation [11], convection diffusion

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equation [12], Fokker Planck equation [13]. Some of the FDEs do not have exact solution, therefore it is required to work on computational methods to solve the mentioned equations such as solving nonlinear fractional diffusion wave equation with homotopy analysis technique [14], solving PDEs of fractal order by Adomian decomposition method [15]. In [1], the authors have given a bioreactor model but they do not consider the death rate of bacteria and also general configuration of the reactor. We have provided the bioreactor model with the fractal-fractional derivatives (FFD). The model with fractal-fractional derivatives has never been analysed so far. Our model includes the death rate of bacteria which is important in environment of the process. We also consider general configuration of the reactor where our model includes a membrane and continuous reactor. Additionally, we fractionalize the model and apply a novel computational technique to get the computational simulations.

We organize our manuscript as follow. Problem formulation is done in Section 2. In Section 3 we have discussed the analysis of the model in the classical case and presented the equilibria and stability analysis. Sections 4, 5 and 6 deals with analysis of the model with three different kernels viz the power-law kernel, the exponential-decay kernel and the Mittag-Leffler kernel respectively and in section 7 we demonstrate the computational simulations.

2. Preliminaries

The following definitions of FFD and fractal-fractional integral (FFI) with three different kernels are taken from [16] .

Definition 2.1. *The FFD with power-law type kernel is described as:*

$${}_c^{FFP}D_t^{\alpha,\eta}f(t) = \frac{1}{1-\alpha} \frac{d}{dt^\eta} \int_c^t f(s)(t-s)^{-\alpha}ds, \quad 0 < \alpha, \eta \leq 1, \quad (1)$$

where,

$$\frac{df(s)}{ds^\eta} = \lim_{t \rightarrow s} \frac{f(t) - f(s)}{t^\eta - s^\eta} \quad (2)$$

Definition 2.2. *The FFD with exponential-decay type kernel is described as:*

$${}_c^{FFE}D_t^{\alpha,\eta}f(t) = \frac{M_I(\alpha)}{1-\alpha} \frac{d}{dt^\eta} \int_c^t f(s) \exp\left(\frac{-\alpha}{1-\alpha}(t-s)\right)ds, \quad 0 < \alpha, \eta \leq 1. \quad (3)$$

Definition 2.3. *The FFD with Mittag-Leffler type kernel is described as:*

$${}^{FFM}_c D_t^{\alpha, \eta} f(t) = \frac{AB(\alpha)}{1-\alpha} \frac{d}{dt} \int_c^t f(s) E_\alpha \left(\frac{-\alpha}{1-\alpha} (t-s)^\alpha \right) ds, \quad 0 < \alpha, \eta \leq 1, \quad (4)$$

where, $AB(\alpha) = 1 - \alpha + \frac{\alpha}{\Gamma(\alpha)}$.

Definition 2.4. The FFI with power-law type kernel is described as:

$${}^{FFP}_0 I_t^{\alpha, \eta} f(t) = \frac{\eta}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} s^{\tau-1} \phi(s) ds. \quad (5)$$

Definition 2.5. The FFI with exponential-decay type kernel is described as:

$${}^{FFE}_0 I_t^{\alpha, \eta} f(t) = \frac{\alpha \eta}{M_1(\alpha)} \int_0^t s^{\alpha-1} f(s) ds + \frac{\tau(1-\alpha)t^{\tau-1}}{M_1(\alpha)} \phi(t). \quad (6)$$

Definition 2.6. The FFI with Mittag-Leffler type kernel is described as:

$${}^{FFM}_0 I_t^{\alpha, \eta} f(t) = \frac{\alpha \eta}{AB(\alpha)} \int_0^t s^{\alpha-1} f(s) (t-s)^{\alpha-1} ds + \frac{\tau(1-\alpha)t^{\tau-1}}{AB(\alpha)} f(t). \quad (7)$$

3. Formation of the model

Here, we provide the model that will be examined in this study. The three-dimensional model is provided as follows:

$$\frac{dS_{ph}}{dt} = D(S_{ph0} - S_{ph}) - k_{ph} \cdot \mu(S_{ph}, S_{cr}) \cdot X, \quad (8)$$

$$\frac{dS_{cr}}{dt} = D(S_{cr0} - S_{cr}) - k_{cr} \cdot \mu(S_{ph}, S_{cr}) \cdot X, \quad (9)$$

$$\frac{dX}{dt} = -D\beta X + \mu(S_{ph}, S_{cr}) X, \quad (10)$$

$$\mu(S_{ph}, S_{cr}) = \frac{\mu_{max(ph)} S_{ph}}{K_{s(ph)} + S_{ph} + \frac{S_{ph}^2}{k_{i(ph)}} + I_{cr/ph} S_{cr}} + \frac{\mu_{max(cr)} S_{cr}}{K_{s(cr)} + S_{cr} + \frac{S_{cr}^2}{k_{i(cr)}} + I_{ph/cr} S_{ph}}, \quad (11)$$

The model parameters and variables are detailed in [1]. The parameter β is presented in the general configuration. When $\beta = 1$ we have continued the reactor. When $\beta = 0$ we have a membrane reactor.

4. Analysis of the model in classical sense

We will now start by performing a traditional analysis of the model's attributes.

4.1. Equilibria and Stability analysis

We take into account how many model (8- 10) equilibrium solutions there are. The model clearly has a branch of the washout specified by: ,

$$E_0 = (S_{ph}, S_{cr}, X) = (S_{ph0}, S_{cr0}, 0). \quad (12)$$

We obtain the steady state solution of (8- 10) by setting to zero the right side. From the model (8- 10), we have,

$$\begin{aligned} S_{cr} &= \frac{S_{cr0}k_{ph} + k_{cr}(S_{ph} - S_{ph0})}{k_{ph}}, \\ X &= \frac{D(S_{ph0} - S_{ph})}{k_{ph}(\beta D)}. \end{aligned} \quad (13)$$

$$\begin{aligned} f = \begin{pmatrix} -k_{cr}\mu(s_{ph}, s_{cr})X \\ \mu(s_{ph}, s_{cr})X \end{pmatrix} &\rightarrow F = \begin{bmatrix} \frac{\partial \mu(s_{ph}, s_{cr})(-k_{cr})X}{\partial (s_{ph}, s_{cr})X} & -k_{cr}\mu(s_{ph}, s_{cr}) \\ \frac{\partial \mu(s_{ph}, s_{cr})X}{\partial (s_{ph}, s_{cr})X} & \mu(s_{ph}, s_{cr})k_{cr}(s_{ph}, s_{cr}) \end{bmatrix} \\ V = \begin{pmatrix} -D(s_{cr0} - s_{cr}) \\ D\beta X \end{pmatrix} &\rightarrow V = \begin{bmatrix} D & 0 \\ 0 & D\beta \end{bmatrix}, V^{-1} = \begin{bmatrix} D\beta & 0 \\ 0 & D \end{bmatrix} \\ FV^{-1} &= \begin{bmatrix} 0 & -k_{cr}\mu(s_{ph}, s_{cr}) \\ 0 & \mu(s_{ph}, s_{cr}) \end{bmatrix} \begin{bmatrix} D & 0 \\ 0 & D\beta \end{bmatrix} = \begin{bmatrix} 0 & -Dk_{cr}\mu(s_{ph}, s_{cr}) \\ 0 & D\mu(s_{ph}, s_{cr}) \end{bmatrix} \\ \det \left[FV^{-1} - \lambda I_2 \right] &= 0, \begin{vmatrix} -\lambda & -Dk_{cr}\mu(s_{ph}, s_{cr}) \\ 0 & D\mu(s_{ph}, s_{cr}) - \lambda \end{vmatrix} = 0 \end{aligned}$$

Thus, we obtain $\lambda_1 = 0$, $\lambda_2 = D\mu(s_{ph}, s_{cr}) = R_0$

Lemma 4.0.1. *The steady state solution E_0 is locally asymptotically stable when $D > D_{cr}$ and is unstable when $D < D_{cr}$.*

Proof. We have

$$E_0 = (s_{ph}, s_{cr}, x) = (s_{ph0}, s_{cr0}, 0)$$

$$J(E_0) = \begin{bmatrix} -D - \frac{\partial \mu(s_{ph}, s_{cr})}{\partial s_{ph}} k_{ph} x & -\frac{\partial \mu(s_{ph}, s_{cr})}{\partial s_{ph}} k_{ph} x & -\mu(s_{ph}, s_{cr}) k_{ph} \\ -k_{cr} \frac{\partial \mu(s_{ph}, s_{cr})}{\partial s_{ph}} x & -D - \frac{\partial \mu(s_{ph}, s_{cr})}{\partial s_{ph}} k_{cr} x & -\mu(s_{ph}, s_{cr}) k_{cr} \\ \frac{\partial \mu(s_{ph}, s_{cr})}{\partial s_{ph}} x & -\frac{\partial \mu(s_{ph}, s_{cr})}{\partial s_{ph}} x & -D\beta + \mu(s_{ph}, s_{cr}) \end{bmatrix}$$

$$J(E_0) = \begin{bmatrix} -D & 0 & -\mu(s_{ph0}, s_{cr0}) k_{ph} \\ 0 & -D & -\mu(s_{ph0}, s_{cr0}) k_{cr} \\ 0 & 0 & -D\beta + \mu(s_{ph0}, s_{cr0}) \end{bmatrix}$$

where

$$\mu(s_{ph}, s_{cr}) = \frac{\mu_{max(ph)} s_{ph}}{K_{s(ph)} + s_{ph} + \frac{s_{ph}^2}{K_{i(ph)}} + I_{cr/ph} s_{cr}} + \frac{\mu_{max(cr)} s_{ph}}{K_{s(cr)} + s_{cr} + \frac{s_{cr}^2}{K_{i(cr)}} + I_{ph/cr} s_{ph}}$$

$$\det[J(E_0) - \lambda I_3] = \begin{vmatrix} -D - \lambda & 0 & -\mu(s_{ph}, s_{cr}) k_{ph} \\ 0 & -D - \lambda & -\mu(s_{ph}, s_{cr}) k_{cr} \\ 0 & 0 & \mu(s_{ph}, s_{cr}) - D\beta - \lambda \end{vmatrix} = 0$$

$$= (-D - \lambda)(-D - \lambda)(\mu(s_{ph}, s_{cr}) - D\beta - \lambda) = 0$$

$$\lambda_1 = -D, \quad \lambda_2 = -D, \quad \lambda_3 = -\beta D + \mu(s_{ph}, s_{cr})$$

and

$$\begin{aligned} \mu(s_{ph}, s_{cr}) &= \frac{s_{ph0}^2}{K_{i(ph)}} + I_{cr/ph} s_{cr0})^{-1} \\ &+ \frac{s_{cr0}^2}{K_{i(ph)}} + I_{ph/cr} s_{ph0})^{-1} \\ D_{cr} &= \frac{k_{icr} k_{ph} (s_{cr0} k_{ph} - s_{ph0} k_{cr})^{-1} \max_{cr}}{\left[k_{icr} k_{ph} (K_{scr} k_{ph} + s_{cr0} k_{ph} - s_{ph0} k_{cr}) + (s_{cr} k_{ph} - s_{ph0} k_{cr})^2 \right] \beta} \end{aligned}$$

If $D > D_{cr}$, then $\lambda_3 < 0$. Thus, all eigenvalues are negative. This presents that the steady state solution E_0 is locally asymptotically stable. \square

5. Analysis of the Model with the Power-Law Kernel

Here we analyze the model with FFD using the power-law kernel as:

$${}_0^{FFP}D_t^{\alpha,\eta}S_{ph} = D(S_{ph0} - S_{ph}) - k_{ph} \cdot \mu(S_{ph}, S_{cr}) \cdot X, \quad (14)$$

$${}_0^{FFP}D_t^{\alpha,\eta}S_{cr} = D(S_{cr0} - S_{cr}) - k_{cr} \cdot \mu(S_{ph}, S_{cr}) \cdot X, \quad (15)$$

$${}_0^{FFP}D_t^{\alpha,\eta}X = -D\beta X + \mu(S_{ph}, S_{cr})X \quad (16)$$

We have [16]:

$$D^\eta f(t) = \frac{f'(t)}{\eta t^{\eta-1}}. \quad (17)$$

Then, we acquire

$${}_0^{RL}D_t^\alpha S_{ph} = \eta t^{\eta-1} \left(D(S_{ph0} - S_{ph}) - k_{ph} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (18)$$

$${}_0^{RL}D_t^\alpha S_{cr} = \eta t^{\eta-1} \left(D(S_{cr0} - S_{cr}) - k_{cr} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (19)$$

$${}_0^{RL}D_t^\alpha X = \eta t^{\eta-1} \left(-D\beta X + \mu(S_{ph}, S_{cr})X \right) \quad (20)$$

For simplicity, we define

$$A(t, S_{ph}, S_{cr}, X) = \eta t^{\eta-1} \left(D(S_{ph0} - S_{ph}) - k_{ph} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (21)$$

$$B(t, S_{ph}, S_{cr}, X) = \eta t^{\eta-1} \left(D(S_{cr0} - S_{cr}) - k_{cr} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (22)$$

$$C(t, S_{ph}, S_{cr}, X) = \eta t^{\eta-1} \left(-D\beta X + \mu(S_{ph}, S_{cr})X \right) \quad (23)$$

Then, we obtain

$${}_0^{RL}D_t^\alpha S_{ph} = A(t, S_{ph}, S_{cr}, X) \quad (24)$$

$${}_0^{RL}D_t^\alpha S_{cr} = B(t, S_{ph}, S_{cr}, X) \quad (25)$$

$${}_0^{RL}D_t^\alpha X = C(t, S_{ph}, S_{cr}, X) \quad (26)$$

Applying the Riemann-Liouville integral yields:

$$S_{ph}(t) - S_{ph}(0) = \frac{1}{\Gamma(\alpha)} \int_0^t A(\tau, S_{ph}, S_{cr}, X)(t - \tau)^{\alpha-1} d\tau \quad (27)$$

$$S_{cr}(t) - S_{cr}(0) = \frac{1}{\Gamma(\alpha)} \int_0^t B(\tau, S_{ph}, S_{cr}, X)(t - \tau)^{\alpha-1} d\tau \quad (28)$$

$$X(t) - X(0) = \frac{1}{\Gamma(\alpha)} \int_0^t C(\tau, S_{ph}, S_{cr}, X)(t - \tau)^{\alpha-1} d\tau \quad (29)$$

Discretizing the above equations at t_{n+1} , we get:

$$S_{ph}(t_{n+1}) - S_{ph}(0) = \frac{1}{\Gamma(\alpha)} \int_0^{t_{n+1}} A(\tau, S_{ph}, S_{cr}, X)(t_{n+1} - \tau)^{\alpha-1} d\tau \quad (30)$$

$$S_{cr}(t_{n+1}) - S_{cr}(0) = \frac{1}{\Gamma(\alpha)} \int_0^{t_{n+1}} B(\tau, S_{ph}, S_{cr}, X)(t_{n+1} - \tau)^{\alpha-1} d\tau \quad (31)$$

$$X(t_{n+1}) - X(0) = \frac{1}{\Gamma(\alpha)} \int_0^{t_{n+1}} C(\tau, S_{ph}, S_{cr}, X)(t_{n+1} - \tau)^{\alpha-1} d\tau \quad (32)$$

$$S_{ph}(t_{n+1}) - S_{ph}(0) = \frac{1}{\Gamma(\alpha)} \sum_{j=0}^n \int_{t_j}^{t_{j+1}} A(\tau, S_{ph}, S_{cr}, X)(t_{n+1} - \tau)^{\alpha-1} d\tau \quad (33)$$

$$S_{cr}(t_{n+1}) - S_{cr}(0) = \frac{1}{\Gamma(\alpha)} \sum_{j=0}^n \int_{t_j}^{t_{j+1}} B(\tau, S_{ph}, S_{cr}, X)(t_{n+1} - \tau)^{\alpha-1} d\tau \quad (34)$$

$$X(t_{n+1}) - X(0) = \frac{1}{\Gamma(\alpha)} \sum_{j=0}^n \int_{t_j}^{t_{j+1}} C(\tau, S_{ph}, S_{cr}, X)(t_{n+1} - \tau)^{\alpha-1} d\tau \quad (35)$$

Two-step Lagrange polynomial is used as:

$$p_j(\tau, S_{ph}, S_{cr}, X) = \frac{\tau - t_{j-1}}{t_j - t_{j-1}} A(t_j, S_{ph}, S_{cr}, X) - \frac{\tau - t_j}{t_j - t_{j-1}} A(t_{j-1}, S_{ph}, S_{cr}, X) \quad (36)$$

$$q_j(\tau, S_{ph}, S_{cr}, X) = \frac{\tau - t_{j-1}}{t_j - t_{j-1}} B(t_j, S_{ph}, S_{cr}, X) - \frac{\tau - t_j}{t_j - t_{j-1}} B(t_{j-1}, S_{ph}, S_{cr}, X) \quad (37)$$

$$s_j(\tau, S_{ph}, S_{cr}, X) = \frac{\tau - t_{j-1}}{t_j - t_{j-1}} C(t_j, S_{ph}, S_{cr}, X) - \frac{\tau - t_j}{t_j - t_{j-1}} C(t_{j-1}, S_{ph}, S_{cr}, X) \quad (38)$$

Then, we obtain

$$\begin{aligned}
S_{ph}(t_{n+1}) - S_{ph}(0) &= \frac{1}{\Gamma(\alpha)} \sum_{j=0}^n \int_{t_j}^{t_{j+1}} p(\tau, S_{ph}, S_{cr}, X)(t_{n+1} - \tau)^{\alpha-1} d\tau \\
&= \sum_{j=0}^n \left[\frac{h^\alpha A(t_j, S_{ph}, S_{cr}, X)}{\Gamma(\alpha + 2)} ((n+1-j)^\alpha (n-j+2+\alpha) \right. \\
&\quad \left. -(n-j)^\alpha (n-j+2+2\alpha)) \right] \\
&\quad - \sum_{j=0}^n \left[\frac{h^\alpha A(t_{j-1}, S_{ph}, S_{cr}, X)}{\Gamma(\alpha + 2)} ((n+1-j)^{\alpha+1} \right. \\
&\quad \left. -(n-j)^\alpha (n-j+1+\alpha)) \right]
\end{aligned}$$

$$\begin{aligned}
S_{cr}(t_{n+1}) - S_{cr}(0) &= \frac{1}{\Gamma(\alpha)} \sum_{j=0}^n \int_{t_j}^{t_{j+1}} q(\tau, S_{ph}, S_{cr}, X)(t_{n+1} - \tau)^{\alpha-1} d\tau \\
&= \sum_{j=0}^n \left[\frac{h^\alpha B(t_j, S_{ph}, S_{cr}, X)}{\Gamma(\alpha + 2)} ((n+1-j)^\alpha (n-j+2+\alpha) \right. \\
&\quad \left. -(n-j)^\alpha (n-j+2+2\alpha)) \right] \\
&\quad - \sum_{j=0}^n \left[\frac{h^\alpha B(t_{j-1}, S_{ph}, S_{cr}, X)}{\Gamma(\alpha + 2)} ((n+1-j)^{\alpha+1} \right. \\
&\quad \left. -(n-j)^\alpha (n-j+1+\alpha)) \right]
\end{aligned}$$

$$\begin{aligned}
X(t_{n+1}) - X(0) &= \frac{1}{\Gamma(\alpha)} \sum_{j=0}^n \int_{t_j}^{t_{j+1}} s(\tau, S_{ph}, S_{cr}, X)(t_{n+1} - \tau)^{\alpha-1} d\tau \\
&= \sum_{j=0}^n \left[\frac{h^\alpha C(t_j, S_{ph}, S_{cr}, X)}{\Gamma(\alpha + 2)} ((n+1-j)^\alpha (n-j+2+\alpha) \right. \\
&\quad \left. -(n-j)^\alpha (n-j+2+2\alpha)) \right] \\
&\quad - \sum_{j=0}^n \left[\frac{h^\alpha C(t_{j-1}, S_{ph}, S_{cr}, X)}{\Gamma(\alpha + 2)} ((n+1-j)^{\alpha+1} \right. \\
&\quad \left. -(n-j)^\alpha (n-j+1+\alpha)) \right]
\end{aligned}$$

Thus, the computational scheme for the model with power law kernel has been obtained. We used this scheme and obtained Figures 1-4.

6. Analysis of the Model with the Exponential-Decay Kernel

Next we analyze the model with FFD using the exponential-decay kernel as:

$${}_0^{FFE}D_t^{\alpha,\eta}S_{ph} = D(S_{ph0} - S_{ph}) - k_{ph} \cdot \mu(S_{ph}, S_{cr}) \cdot X, \quad (39)$$

$${}_0^{FFE}D_t^{\alpha,\eta}S_{cr} = D(S_{cr0} - S_{cr}) - k_{cr} \cdot \mu(S_{ph}, S_{cr}) \cdot X, \quad (40)$$

$${}_0^{FFE}D_t^{\alpha,\eta}X = -D\beta X + \mu(S_{ph}, S_{cr})X \quad (41)$$

The relationship between the fractal derivative and the classical derivative produces:

$${}_0^{CF}D_t^\alpha S_{ph} = \eta t^{\eta-1} \left(D(S_{ph0} - S_{ph}) - k_{ph} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (42)$$

$${}_0^{CF}D_t^\alpha S_{cr} = \eta t^{\eta-1} \left(D(S_{cr0} - S_{cr}) - k_{cr} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (43)$$

$${}_0^{CF}D_t^\alpha X = \eta t^{\eta-1} \left(-D\beta X + \mu(S_{ph}, S_{cr})X \right) \quad (44)$$

For simplicity, we define

$$K(t, S_{ph}, S_{cr}, X) = \eta t^{\eta-1} \left(D(S_{ph0} - S_{ph}) - k_{ph} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (45)$$

$$L(t, S_{ph}, S_{cr}, X) = \eta t^{\eta-1} \left(D(S_{cr0} - S_{cr}) - k_{cr} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (46)$$

$$M(t, S_{ph}, S_{cr}, X) = \eta t^{\eta-1} \left(-D\beta X + \mu(S_{ph}, S_{cr})X \right) \quad (47)$$

Then, we obtain

$${}_0^{CF}D_t^\alpha S_{ph} = K(t, S_{ph}, S_{cr}, X) \quad (48)$$

$${}_0^{CF}D_t^\alpha S_{cr} = L(t, S_{ph}, S_{cr}, X) \quad (49)$$

$${}_0^{CF}D_t^\alpha X = M(t, S_{ph}, S_{cr}, X) \quad (50)$$

Applying the CF integral yields [17]:

$$\begin{aligned}
S_{ph}(t) - S_{ph}(0) &= \frac{1-\alpha}{M(\alpha)} K(t, S_{ph}, S_{cr}, X) + \frac{\alpha}{M(\alpha)} \int_0^t K(\tau, S_{ph}, S_{cr}, X) d\tau \\
S_{cr}(t) - S_{cr}(0) &= \frac{1-\alpha}{M(\alpha)} L(t, S_{ph}, S_{cr}, X) + \frac{\alpha}{M(\alpha)} \int_0^t L(\tau, S_{ph}, S_{cr}, X) d\tau \\
X(t) - X(0) &= \frac{1-\alpha}{M(\alpha)} M(t, S_{ph}, S_{cr}, X) + \frac{\alpha}{M(\alpha)} \int_0^t M(\tau, S_{ph}, S_{cr}, X) d\tau
\end{aligned}$$

Discretizing the above equations at t_{n+1} and t_n we get:

$$\begin{aligned}
S_{ph}^{n+1} &= S_{ph}^0 + \frac{1-\alpha}{M(\alpha)} K(t_n, S_{ph}^n, S_{cr}^n, X^n) \\
&\quad + \frac{\alpha}{M(\alpha)} \int_0^{t_{n+1}} K(\tau, S_{ph}, S_{cr}, X) d\tau \\
S_{cr}^{n+1} &= S_{cr}^0 + \frac{1-\alpha}{M(\alpha)} L(t_n, S_{ph}^n, S_{cr}^n, X^n) \\
&\quad + \frac{\alpha}{M(\alpha)} \int_0^{t_{n+1}} L(\tau, S_{ph}, S_{cr}, X) d\tau \\
X^{n+1} &= X^0 + \frac{1-\alpha}{M(\alpha)} M(t_n, S_{ph}^n, S_{cr}^n, X^n) \\
&\quad + \frac{\alpha}{M(\alpha)} \int_0^{t_{n+1}} M(\tau, S_{ph}, S_{cr}, X) d\tau
\end{aligned}$$

and

$$\begin{aligned}
S_{ph}^n &= S_{ph}^0 + \frac{1-\alpha}{M(\alpha)} K(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \\
&\quad + \frac{\alpha}{M(\alpha)} \int_0^{t_n} K(\tau, S_{ph}, S_{cr}, X) d\tau \\
S_{cr}^n &= S_{cr}^0 + \frac{1-\alpha}{M(\alpha)} L(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \\
&\quad + \frac{\alpha}{M(\alpha)} \int_0^{t_n} L(\tau, S_{ph}, S_{cr}, X) d\tau \\
X^n &= X^0 + \frac{1-\alpha}{M(\alpha)} M(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \\
&\quad + \frac{\alpha}{M(\alpha)} \int_0^{t_n} M(\tau, S_{ph}, S_{cr}, X) d\tau
\end{aligned}$$

Thus, we reach

$$\begin{aligned}
S_{ph}^{n+1} &= S_{ph}^n + \frac{1-\alpha}{M(\alpha)} \left(K(t_n, S_{ph}^n, S_{cr}^n, X^n) - K(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \right) \\
&\quad + \frac{\alpha}{M(\alpha)} \int_{t_n}^{t_{n+1}} K(\tau, S_{ph}, S_{cr}, X) d\tau \\
S_{cr}^{n+1} &= S_{cr}^n + \frac{1-\alpha}{M(\alpha)} \left(L(t_n, S_{ph}^n, S_{cr}^n, X^n) - L(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \right) \\
&\quad + \frac{\alpha}{M(\alpha)} \int_{t_n}^{t_{n+1}} L(\tau, S_{ph}, S_{cr}, X) d\tau \\
X^{n+1} &= X^n + \frac{1-\alpha}{M(\alpha)} \left(M(t_n, S_{ph}^n, S_{cr}^n, X^n) - M(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \right) \\
&\quad + \frac{\alpha}{M(\alpha)} \int_{t_n}^{t_{n+1}} M(\tau, S_{ph}, S_{cr}, X) d\tau
\end{aligned}$$

Using the two-step Lagrange polynomial yields:

$$\begin{aligned}
S_{ph}^{n+1} &= S_{ph}^n + \frac{1-\alpha}{M(\alpha)} \left(K(t_n, S_{ph}^n, S_{cr}^n, X^n) - K(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \right) \\
&\quad + \frac{\alpha}{M(\alpha)} \left(\frac{3h}{2} K(t_n, S_{ph}^n, S_{cr}^n, X^n) - \frac{h}{2} K(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \right) \\
S_{cr}^{n+1} &= S_{cr}^n + \frac{1-\alpha}{M(\alpha)} \left(L(t_n, S_{ph}^n, S_{cr}^n, X^n) - L(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \right) \\
&\quad + \frac{\alpha}{M(\alpha)} \left(\frac{3h}{2} L(t_n, S_{ph}^n, S_{cr}^n, X^n) - \frac{h}{2} L(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \right) \\
X^{n+1} &= X^n + \frac{1-\alpha}{M(\alpha)} \left(M(t_n, S_{ph}^n, S_{cr}^n, X^n) - M(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \right) \\
&\quad + \frac{\alpha}{M(\alpha)} \left(\frac{3h}{2} M(t_n, S_{ph}^n, S_{cr}^n, X^n) - \frac{h}{2} M(t_{n-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1}) \right)
\end{aligned}$$

As a result, the model's computational scheme for the exponential decay kernel has been discovered.

We used this scheme and obtained Figures 5-8.

7. Analysis of the Model with the Mittag-Leffler Kernel

Now we analyze the model with FFD using the Mittag-Leffler kernel as:

$${}_0^{FFM}D_t^{\alpha,\eta} S_{ph} = D(S_{ph0} - S_{ph}) - k_{ph} \cdot \mu(S_{ph}, S_{cr}) \cdot X, \quad (51)$$

$${}_0^{FFM}D_t^{\alpha,\eta} S_{cr} = D(S_{cr0} - S_{cr}) - k_{cr} \cdot \mu(S_{ph}, S_{cr}) \cdot X, \quad (52)$$

$${}_0^{FFM}D_t^{\alpha,\eta} X = -D\beta X + \mu(S_{ph}, S_{cr}) X \quad (53)$$

Then, we obtain

$${}_0^{AB}D_t^\alpha S_{ph} = \eta t^{\eta-1} \left(D(S_{ph0} - S_{ph}) - k_{ph} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (54)$$

$${}_0^{AB}D_t^\alpha S_{cr} = \eta t^{\eta-1} \left(D(S_{cr0} - S_{cr}) - k_{cr} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (55)$$

$${}_0^{AB}D_t^\alpha X = \eta t^{\eta-1} \left(-D\beta X + \mu(S_{ph}, S_{cr}) X \right) \quad (56)$$

For simplicity, we define

$$Y(t, S_{ph}, S_{cr}, X) = \eta t^{\eta-1} \left(D(S_{ph0} - S_{ph}) - k_{ph} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (57)$$

$$Z(t, S_{ph}, S_{cr}, X) = \eta t^{\eta-1} \left(D(S_{cr0} - S_{cr}) - k_{cr} \cdot \mu(S_{ph}, S_{cr}) \cdot X \right), \quad (58)$$

$$T(t, S_{ph}, S_{cr}, X) = \eta t^{\eta-1} \left(-D\beta X + \mu(S_{ph}, S_{cr}) X \right) \quad (59)$$

Then, we get

$${}_0^{AB}D_t^\alpha S_{ph} = Y(t, S_{ph}, S_{cr}, X), \quad (60)$$

$${}_0^{AB}D_t^\alpha S_{cr} = Z(t, S_{ph}, S_{cr}, X), \quad (61)$$

$${}_0^{AB}D_t^\alpha X = T(t, S_{ph}, S_{cr}, X) \quad (62)$$

Applying the AB integral gives,

$$\begin{aligned} S_{ph}(t) - S_{ph}(0) &= \frac{1-\alpha}{AB(\alpha)} Y(t, S_{ph}, S_{cr}, X) + \frac{\alpha}{AB(\alpha)\Gamma(\alpha)} \int_0^t (t-p)^{\alpha-1} Y(p, S_{ph}, S_{cr}, X) dp \\ S_{cr}(t) - S_{cr}(0) &= \frac{1-\alpha}{AB(\alpha)} Z(t, S_{ph}, S_{cr}, X) + \frac{\alpha}{AB(\alpha)\Gamma(\alpha)} \int_0^t (t-p)^{\alpha-1} Z(p, S_{ph}, S_{cr}, X) dp \\ X(t) - X(0) &= \frac{1-\alpha}{AB(\alpha)} T(t, S_{ph}, S_{cr}, X) + \frac{\alpha}{AB(\alpha)\Gamma(\alpha)} \int_0^t (t-p)^{\alpha-1} T(p, S_{ph}, S_{cr}, X) dp \end{aligned}$$

Discretizing the above equations at t_{n+1} , we get:

$$\begin{aligned}
S_{ph}^{n+1} &= S_{ph}^0 + \frac{1-\alpha}{AB(\alpha)} Y(t_{n+1}, S_{ph}^n, S_{cr}^n, X^n) \\
&\quad + \frac{\alpha}{AB(\alpha)\Gamma(\alpha)} \int_0^{t_{n+1}} (t_{n+1}-p)^{\alpha-1} Y(p, S_{ph}, S_{cr}, X) dp \\
S_{cr}^{n+1} &= S_{cr}^0 + \frac{1-\alpha}{AB(\alpha)} Z(t_{n+1}, S_{ph}^n, S_{cr}^n, X^n) \\
&\quad + \frac{\alpha}{AB(\alpha)\Gamma(\alpha)} \int_0^{t_{n+1}} (t_{n+1}-p)^{\alpha-1} Z(p, S_{ph}, S_{cr}, X) dp \\
X^{n+1} &= X^0 + \frac{1-\alpha}{AB(\alpha)} T(t_{n+1}, S_{ph}^n, S_{cr}^n, X^n) \\
&\quad + \frac{\alpha}{AB(\alpha)\Gamma(\alpha)} \int_0^{t_{n+1}} (t_{n+1}-p)^{\alpha-1} T(p, S_{ph}, S_{cr}, X) dp
\end{aligned}$$

Then, we obtain

$$\begin{aligned}
S_{ph}^{n+1} &= S_{ph}^0 + \frac{1-\alpha}{AB(\alpha)} Y(t_{n+1}, S_{ph}^n, S_{cr}^n, X^n) \\
&\quad + \frac{\alpha}{AB(\alpha)} \sum_{i=0}^n \left[\frac{h^\alpha Y(t_i, S_{ph}^n, S_{cr}^n, X^n)}{\Gamma(\alpha+2)} ((n+1-i)^\alpha (n-i+2+\alpha) \right. \\
&\quad \left. -(n-i)^\alpha (n-i+2+2\alpha)) \right] \\
&\quad - \frac{\alpha}{AB(\alpha)} \sum_{i=0}^n \left[\frac{h^\alpha Y(t_{i-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1})}{\Gamma(\alpha+2)} ((n+1-i)^{\alpha+1} \right. \\
&\quad \left. -(n-i)^\alpha (n-i+1+\alpha)) \right] \\
S_{cr}^{n+1} &= S_{cr}^0 + \frac{1-\alpha}{AB(\alpha)} Z(t_{n+1}, S_{ph}^n, S_{cr}^n, X^n) \\
&\quad + \frac{\alpha}{AB(\alpha)} \sum_{i=0}^n \left[\frac{h^\alpha Z(t_i, S_{ph}^n, S_{cr}^n, X^n)}{\Gamma(\alpha+2)} ((n+1-i)^\alpha (n-i+2+\alpha) \right. \\
&\quad \left. -(n-i)^\alpha (n-i+2+2\alpha)) \right] \\
&\quad - \frac{\alpha}{AB(\alpha)} \sum_{i=0}^n \left[\frac{h^\alpha Z(t_{i-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1})}{\Gamma(\alpha+2)} ((n+1-i)^{\alpha+1} \right. \\
&\quad \left. -(n-i)^\alpha (n-i+1+\alpha)) \right]
\end{aligned}$$

$$\begin{aligned}
X^{n+1} = & X^0 + \frac{1-\alpha}{AB(\alpha)} T(t_{n+1}, S_{ph}^n, S_{cr}^n, X^n) \\
& + \frac{\alpha}{AB(\alpha)} \sum_{i=0}^n \left[\frac{h^\alpha T(t_i, S_{ph}^n, S_{cr}^n, X^n)}{\Gamma(\alpha+2)} ((n+1-i)^\alpha (n-i+2+\alpha) \right. \\
& \quad \left. -(n-i)^\alpha (n-i+2+2\alpha)) \right] \\
& - \frac{\alpha}{AB(\alpha)} \sum_{i=0}^n \left[\frac{h^\alpha T(t_{i-1}, S_{ph}^{n-1}, S_{cr}^{n-1}, X^{n-1})}{\Gamma(\alpha+2)} ((n+1-i)^{\alpha+1} \right. \\
& \quad \left. -(n-i)^\alpha (n-i+1+\alpha)) \right].
\end{aligned}$$

Thus, the computational scheme for the model with Mittag Leffler kernel has been obtained. We used this scheme and obtained Figures 9-12.

Remark 1. *The ability to impactively define models for systems with memory impacts is a key and significant advantage of FFD. Fractal-fractional operators with varied memories are related to various non-local dynamical systems' relaxation processes. Models with FFD are therefore more helpful and impactive.*

8. Results and Discussions

This section includes computational simulations for various fractional order and fractal dimension values. We discuss the results with the three different kernels as described in sections 5, 6 and 7. In these figure α, β and η are between zero and one. In these simulations, β is the parameter given on the model, η is fractal dimension and α is the fractional order. In Figure 1, we show the computational simulations for $\beta = 1$ and the fractal dimension $\eta = 1$ for different values of fractional order α with the power-law kernel. In this figure, we can see the impact of the fractional order α . In Figure 2, we show the computational simulations for $\beta = 1$ and the fractal dimension $\eta = 0.8$ for different values of fractional order α with the power-law kernel. In this figure, we can see the impact of the fractional order α . In Figure 3, we show the computational simulations for $\beta = 0.5$ and the fractal dimension $\eta = 1.0$ for different values of fractional order α with the power-law kernel. In this figure, we can see the impact of the fractional order α . In Figure 4, we show the computational simulations for $\beta = 0.5$ and the fractal dimension $\eta = 0.9$ for different values of fractional order α with the power-law kernel. In this figure, we can see the impact of the fractional order α . In Figure 5, we show the computational simulations for $\beta = 1$ and the fractal dimension $\eta = 1$ for different values of fractional order α with the exponential-decay kernel. In this figure, we can see the impact of the

fractional order α . In Figure 6, we show the computational simulations for $\beta = 1$ and the fractal dimension $\eta = 0.7$ for different values of fractional order α with the exponential-decay kernel. In this figure, we can see the impact of the fractional order α . In Figure 7, we show the computational simulations for $\beta = 0.8$ and the fractal dimension $\eta = 1$ for different values of fractional order α with the exponential-decay kernel. In this figure, we can see the impact of the fractional order α . In Figure 8, we show the computational simulations for $\beta = 0.8$ and the fractal dimension $\eta = 0.7$ for different values of fractional order α with the exponential-decay kernel. In this figure, we can see the impact of the fractional order α . In Figure 9, we show the computational simulations for $\beta = 1.0$ and the fractal dimension $\eta = 1.0$ for different values of fractional order α with the Mittag-Leffler kernel. In this figure, we can see the impact of the fractional order α . In Figure 10, we show the computational simulations for $\beta = 1.0$ and the fractal dimension $\eta = 0.5$ for different values of fractional order α with the Mittag-Leffler kernel. In this figure, we can see the impact of the fractional order α . In Figure 11, we show the computational simulations for $\beta = 0.5$ and the fractal dimension $\eta = 1.0$ for different values of fractional order α with the Mittag-Leffler kernel. In this figure, we can see the impact of the fractional order α . In Figure 12, we show the computational simulations for $\beta = 0.5$ and the fractal dimension $\eta = 0.6$ for different values of fractional order α with the Mittag-Leffler kernel. In this figure, we can see the impact of the fractional order α . In these figures, we can also see the impact of the parameter β and the impact of fractal dimension η .

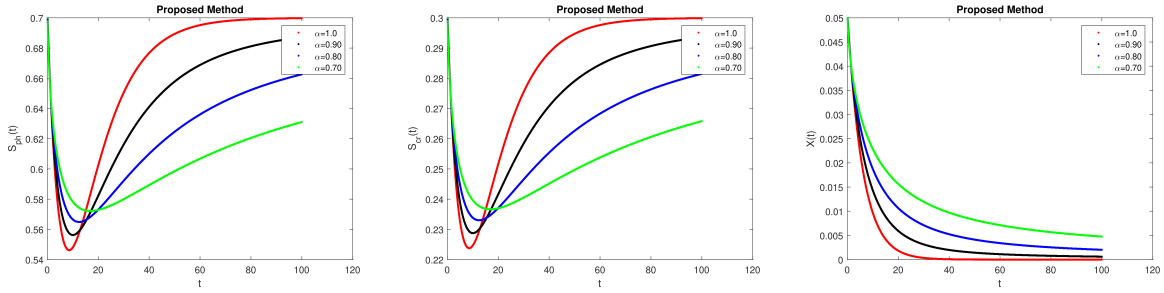


Figure 1: Computational simulations for $\beta = 1$ and the fractal dimension is 1 with the power-law kernel

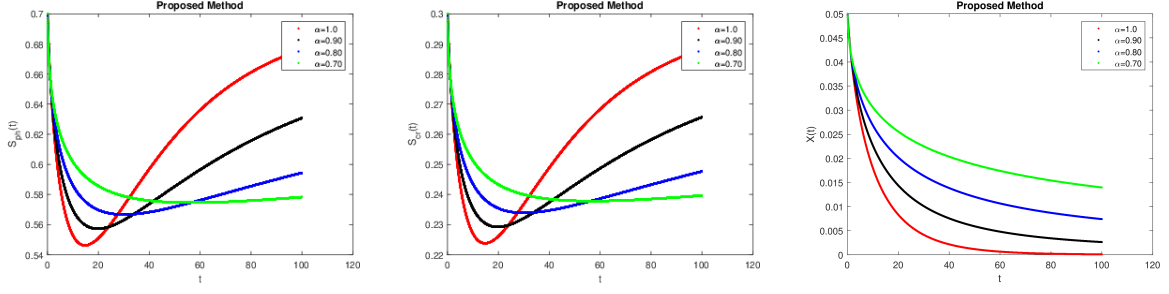


Figure 2: Computational simulations for $\beta = 1$ and the fractal dimension is 0.8 with the power-law kernel

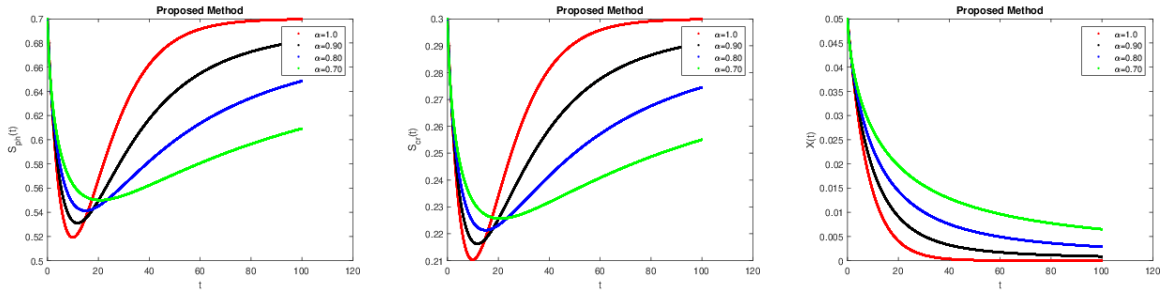


Figure 3: Computational simulations for $\beta = 0.5$ and the fractal dimension is 1 with the power-law kernel

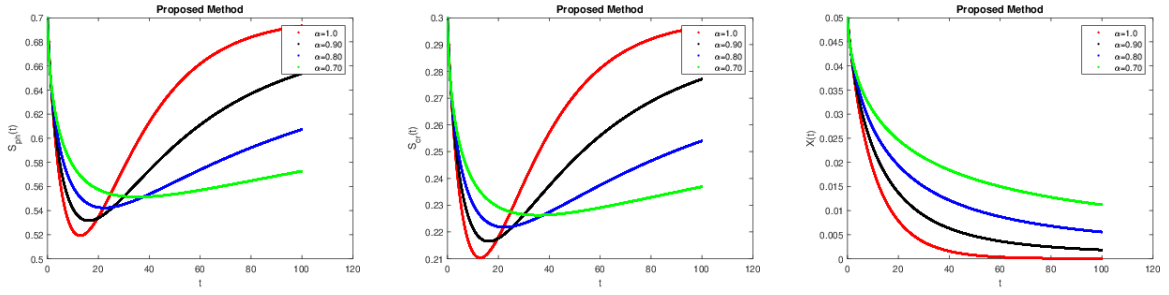


Figure 4: Computational simulations for $\beta = 0.5$ and the fractal dimension is 0.9 with the power-law kernel

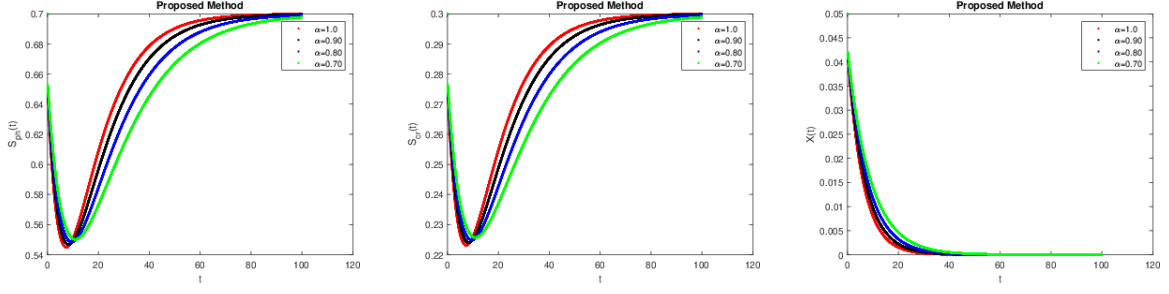


Figure 5: Computational simulations for $\beta = 1.0$ and the fractal dimension is 1 with the exponential-decay kernel

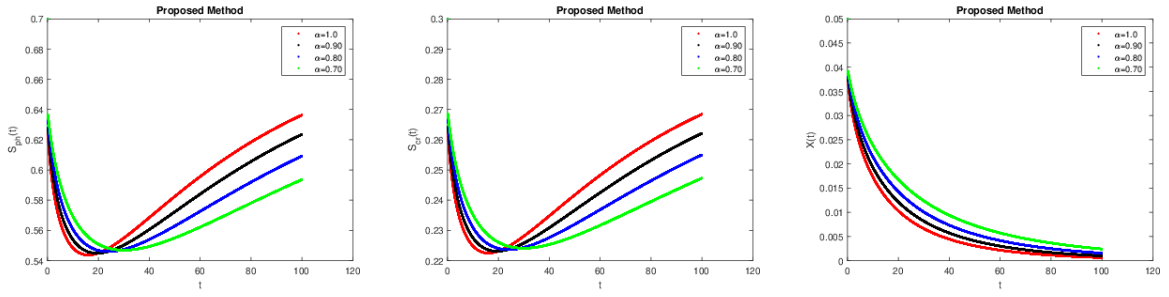


Figure 6: Computational simulations for $\beta = 1.0$ and the fractal dimension is 0.7 with the exponential-decay kernel

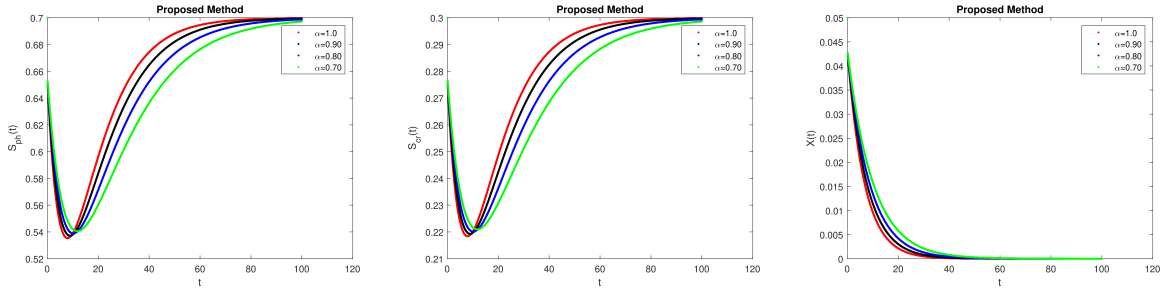


Figure 7: Computational simulations for $\beta = 0.8$ and the fractal dimension is 1.0 with the exponential-decay kernel

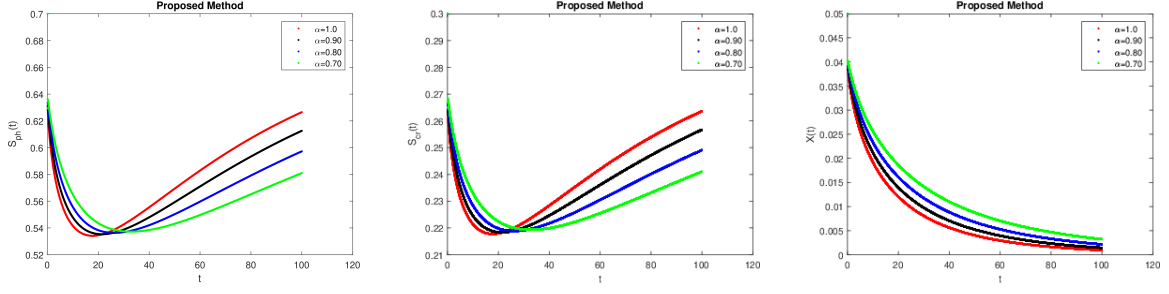


Figure 8: Computational simulations for $\beta = 0.8$ and the fractal dimension is 0.7 with the exponential-decay kernel

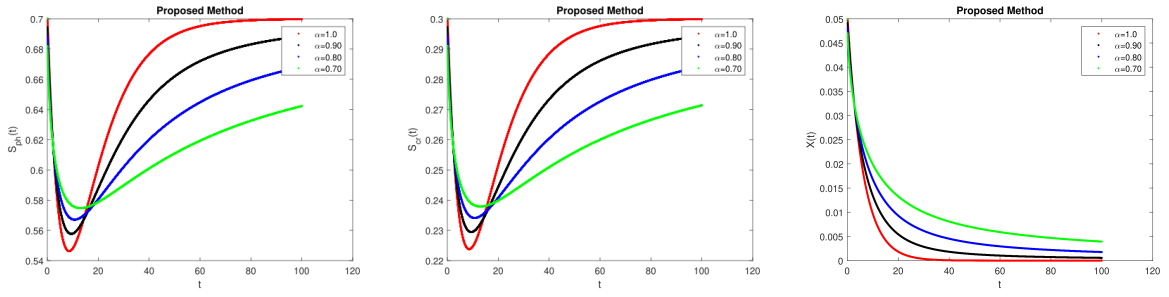


Figure 9: Computational simulations for $\beta = 1.0$ and the fractal dimension is 1.0 with the Mittag-Leffler kernel

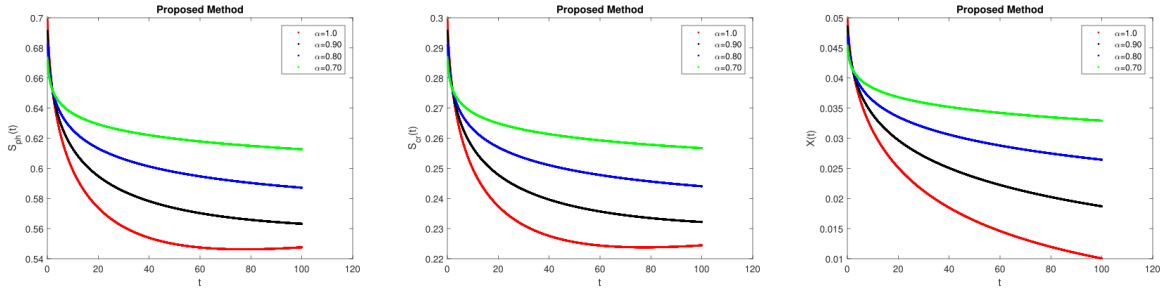


Figure 10: Computational simulations for $\beta = 1.0$ and the fractal dimension is 0.5 with the Mittag-Leffler kernel

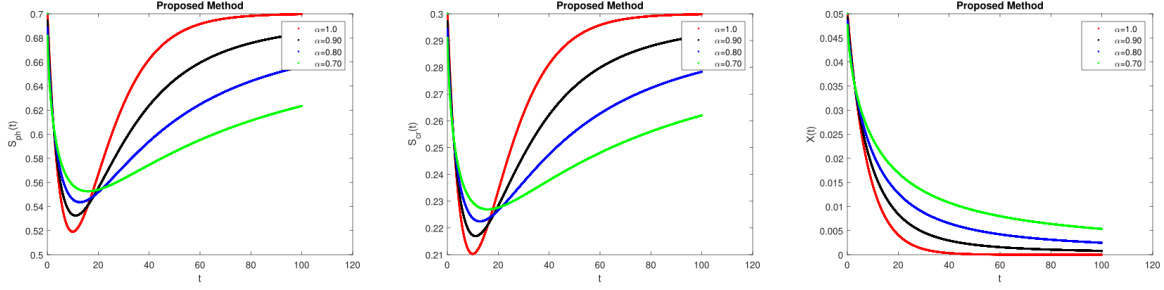


Figure 11: Computational simulations for $\beta = 0.5$ and the fractal dimension is 1.0 with the Mittag-Leffler kernel

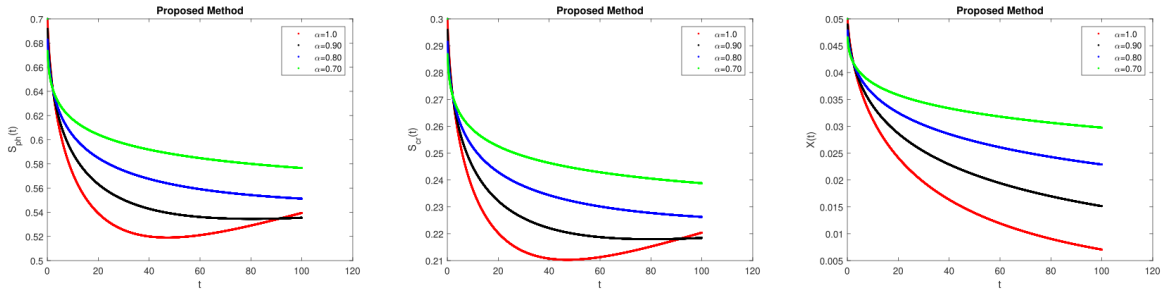


Figure 12: Computational simulations for $\beta = 0.5$ and the fractal dimension is 0.6 with the Mittag-Leffler kernel

9. Conclusion

In a continuously stirred bioreactor, a mathematical model for the breakdown of a phenol and p-cresol mixture was suggested in this manuscript. The model was based on three nonlinear ordinary differential equations. Analysis of their stability and determination of the model's equilibrium points were presented. Utilizing three alternative kernels, we also examined the model with the FFD and looked into the impacts of the fractional order and fractal dimension. For the concentrations of phenol, p-cresol, and biomass, we developed incredibly efficient computational approaches. To demonstrate the accuracy of the suggested technique, we gave the computational simulations for different values of α and β .

Conflict of interest

The authors declare no conflict of interest.

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