# On Invariant Submanifolds of Lorentz Sasakian Space Forms 

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#### Abstract

In this article, invariant submanifolds of Lorentz-Sasakian space forms on the $W_{7}-$ curvature tensor are investigated. For the $W_{7}$-curvature tensor, the pseudoparallel, $2-$ pseudoparallel, Ricci generalized pesudoparallel and $2-$ Ricci generalized pseudoparallel properties of the invariant submanifolds of the Lorentz-Sasakian space form are discussed.


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## 1 Introduction

$\phi$-sectional curvature plays the an important role for Sasakian manifold. If the $\phi$-sectional curvature of a Sasakian manifold is constant,

[^0]then the manifold is a Sasakian-space-form [2]. P. Alegre and D. Blair described generalized Sasakian space forms [11]. P. Alegre and D. Blair obtained important properties of generalized Sasakian space forms in their studies and gave some examples. P. Alegre and A. Carriazo later discussed generalized indefinite Sasakian space forms [10]. Generalized indefinite Sasakian space forms are also called Lorentz-Sasakian space forms, and Lorentz manifolds are of great importance for Einstein's theory of Relativity. Sasakian space forms, generalized Sasakian space forms and Lorentz-Sasakian space forms have been discussed by many scientists and important properties of these manifolds have been obtained ([1],[3],[4],[8],[9]).

Many mathematicians have considered the submanifolds of manifolds such as $K$-paracontak, Lorentzian para-Kenmotsu, almost Kenmotsu and studied their various characterizations ([5],[6],[7]).

In this article, total geodesic submanifolds for Lorentz-Sasakian space forms are investigated. For these submanifolds, pseudoparallel, 2-pseudoparallel, Ricci generalized pseudoparallel and 2-Ricci generalized pseudoparallel invariant submanifolds have been studied and many new results have been obtained. In addition, necessary and sufficient conditions have been obtained for these submanifolds to be total geodesic on the concircular and projective curvature tensors.

## 2 Preliminary

Let $\tilde{M}$ be a $(2 m+1)$-dimensional Lorentz manifold. If the $\tilde{M}$ Lorentz manifold with $(\phi, \xi, \eta, g)$ structure tensors satisfies the following conditions, this manifold is called a Lorentz-Sasakian manifold

$$
\begin{aligned}
& \phi^{2} X_{1}=-X_{1}+\eta\left(X_{1}\right) \xi, \eta(\xi)=1, \eta\left(\phi X_{1}\right)=0, \\
& g\left(\phi X_{1}, \phi X_{2}\right)=g\left(X_{1}, X_{2}\right)+\eta\left(X_{1}\right) \eta\left(X_{2}\right), \eta\left(X_{1}\right)=-g\left(X_{1}, \xi\right), \\
& \left(\tilde{\nabla}_{X_{1}} \phi\right) X_{2}=-g\left(X_{1}, X_{2}\right) \xi-\eta\left(X_{2}\right) X_{1}, \tilde{\nabla}_{X_{1}} \xi=-\phi X_{1},
\end{aligned}
$$

where, $\tilde{\nabla}$ is the Levi-Civita connection according to the Riemann metric $g$.

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The plane section $\Pi$ in $T_{x} \tilde{M}$. If the $\Pi$ plane is spanned by $X_{1}$ and $\phi X_{1}$, this plane is called the $\phi$-section. The curvature of the $\phi$-section is called the $\phi$-sectional curvature. If the Lorentz-Sasakian manifold has a constant $\phi$-sectional curvature, this manifold is called the LorentzSasakian space form and is denoted by $\tilde{M}(c)$. The curvature tensor of the Lorentz-Sasakian space form $\tilde{M}(c)$ is defined as

$$
\begin{aligned}
& \tilde{R}\left(X_{1}, X_{2}\right) X_{3}=\left(\frac{c-3}{4}\right)\left\{g\left(X_{2}, X_{3}\right) X_{1}-g\left(X_{1}, X_{3}\right) X_{2}\right\} \\
& +\left(\frac{c+1}{4}\right)\left\{g\left(X_{1}, \phi X_{3}\right) \phi X_{2}-g\left(X_{2}, \phi X_{3}\right) \phi X_{1}\right. \\
& +2 g\left(X_{1}, \phi X_{2}\right) \phi X_{3}+\eta\left(X_{2}\right) \eta\left(X_{3}\right) X_{1}-\eta\left(X_{1}\right) \eta\left(X_{3}\right) X_{2} \\
& \left.+g\left(X_{1}, X_{3}\right) \eta\left(X_{2}\right) \xi-g\left(X_{2}, X_{3}\right) \eta\left(X_{1}\right) \xi\right\},
\end{aligned}
$$

for all $X_{1}, X_{2}, X_{3} \in \chi(\tilde{M})$.
Lemma 2.1. Let $\tilde{M}(c)$ be the $(2 m+1)$-dimensional Lorentz-Sasakian space form. The following relations are provided for the Lorentz-Sasakian space forms.

$$
\begin{gather*}
\tilde{\nabla} X_{1} \xi=-\phi X_{1}  \tag{1}\\
\left(\tilde{\nabla}_{X_{1}} \phi\right) X_{2}=-g\left(X_{1}, X_{2}\right) \xi-\eta\left(X_{2}\right) X_{1}  \tag{2}\\
\left(\tilde{\nabla}_{X_{1}} \eta\right) X_{2}=g\left(\phi X_{1}, X_{2}\right) \\
\tilde{R}\left(\xi, X_{2}\right) X_{3}=-g\left(X_{2}, X_{3}\right) \xi-\eta\left(X_{3}\right) X_{2}  \tag{3}\\
\tilde{R}\left(\xi, X_{2}\right) \xi=\eta\left(X_{2}\right) \xi-X_{2}  \tag{4}\\
\tilde{R}\left(X_{1}, X_{2}\right) \xi=\eta\left(X_{2}\right) X_{1}-\eta\left(X_{1}\right) X_{2}  \tag{5}\\
S\left(X_{1}, \xi\right)=-\left[\frac{(c+1)-4 m}{2}\right] \eta\left(X_{1}\right) \tag{6}
\end{gather*}
$$

where $\tilde{R}, S$ are the Riemann curvature tensor, Ricci curvature tensor of $\tilde{M}(c)$, respectively.

Let $M$ be the immersed submanifold of the $(2 m+1)$-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. Let the tangent and normal subspaces of $M$ in $\tilde{M}(c)$ be $\Gamma(T M)$ and $\Gamma\left(T^{\perp} M\right)$, respectively. Gauss and Weingarten formulas for $\Gamma(T M)$ and $\Gamma\left(T^{\perp} M\right)$ are

$$
\begin{gather*}
\tilde{\nabla} X_{1} X_{2}=\nabla X_{1} X_{2}+h\left(X_{1}, X_{2}\right),  \tag{7}\\
\tilde{\nabla}_{X_{1}} X_{5}=-A_{X_{5}} X_{1}+\nabla \frac{1}{X_{1}} X_{5},
\end{gather*}
$$

respectively, for all $X_{1}, X_{2} \in \Gamma(T M)$ and $X_{5} \in \Gamma\left(T^{\perp} M\right)$, where $\nabla$ and $\nabla^{\perp}$ are the connections on $M$ and $\Gamma\left(T^{\perp} M\right)$, respectively, $h$ and $A$ are the second fundamental form and the shape operator of $M$. There is a relation

$$
g\left(A_{X_{5}} X_{1}, X_{2}\right)=g\left(h\left(X_{1}, X_{2}\right), X_{5}\right)
$$

between the second basic form and shape operator defined as above. The covariant derivative of the second fundamental form $h$ is defined as

$$
\begin{equation*}
\left(\tilde{\nabla}_{X_{1}} h\right)\left(X_{2}, X_{3}\right)=\nabla \frac{1}{X_{1}} h\left(X_{2}, X_{3}\right)-h\left(\nabla X_{1} X_{2}, X_{3}\right)-h\left(X_{2}, \nabla X_{1} X_{3}\right) . \tag{8}
\end{equation*}
$$

Specifically, if $\tilde{\nabla} h=0, M$ is said to be the parallel second fundamental form or 1-parallel.

Let $R$ be the Riemann curvature tensor of $M$. In this case, the Gauss equation can be expressed as

$$
\begin{aligned}
& \tilde{R}\left(X_{1}, X_{2}\right) X_{3}=R\left(X_{1}, X_{2}\right) X_{3}+A_{h\left(X_{1}, X_{3}\right)} X_{2}-A_{h\left(X_{2}, X_{3}\right)} X_{1} \\
& +\left(\tilde{\nabla}_{X_{1}} h\right)\left(X_{2}, X_{3}\right)-\left(\tilde{\nabla}_{X_{1}} h\right)\left(X_{1}, X_{3}\right) .
\end{aligned}
$$

Let $M$ be a Riemannian manifold, $T$ is $(0, k)$-type tensor field and $A$ is $(0,2)$-type tensor field. In this case, the tensor field $Q(A, T)$ is defined as

$$
\begin{align*}
& Q(A, T)\left(X_{1}, \ldots, X_{k} ; X, Y\right)=-T\left(\left(X \wedge_{A} Y\right) X_{1}, \ldots, X_{k}\right) \\
& -\ldots-T\left(X_{1}, \ldots, X_{k-1},\left(X \wedge_{A} Y\right) X_{k}\right), \tag{9}
\end{align*}
$$

where

$$
\left(X \wedge_{A} Y\right) Z=A(Y, Z) X-A(X, Z) Y
$$

$k \geq 1, X_{1}, X_{2}, \ldots, X_{k}, X, Y \in \Gamma(T M)$.
Let $M$ be the immersed submanifold of a $(2 m+1)$-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. If $\phi\left(T_{X_{1}} M\right) \subset T_{X_{1}} M$ in every $X_{1}$ point, the $M$ manifold is called invariant submanifold. From this section of the article, we will assume that the manifold $M$ is the invariant submanifold of the Lorentz-Sasakian space form $\tilde{M}(c)$. So it is clear from (3) and (9) that

$$
\begin{equation*}
h\left(X_{1}, \xi\right)=0, h\left(\phi X_{1}, X_{2}\right)=h\left(X_{1}, \phi X_{2}\right)=\phi h\left(X_{1}, X_{2}\right) \tag{10}
\end{equation*}
$$

for all $X_{1}, X_{2} \in \Gamma(T M)$.
The tensor defined as

$$
\begin{aligned}
& T\left(X_{1}, X_{2}\right) X_{3}=a_{0} R\left(X_{1}, X_{2}\right) X_{3}+a_{1} S\left(X_{1}, X_{3}\right) X_{2} \\
& +a_{2} S\left(X_{1}, X_{3}\right) X_{2}+a_{3} S\left(X_{1}, X_{2}\right) X_{3}+a_{4} g\left(X_{2}, X_{3}\right) Q X_{1} \\
& +a_{5} g\left(X_{1}, X_{3}\right) Q X_{2}+a_{6} g\left(X_{1}, X_{2}\right) Q X_{3} \\
& +a_{7}\left[g\left(X_{2}, X_{3}\right) X_{1}-g\left(X_{1}, X_{3}\right) X_{2}\right]
\end{aligned}
$$

in an $n$-dimensional $(M, g)$ semi-Riemann manifold is a $(1,3)$-type tensor field, where $a_{0}, a_{1}, \ldots, a_{7}$ are smooth functions in $M$ and also $R, S, Q$ and $r$ are ( 1,1 )-type curvature tensor, Ricci tensor, Ricci operator and scalar curvature, respectively. If we specifically choose $a_{0}=1, a_{1}=$ $-a_{4}=\frac{-1}{2 m}, a_{2}=a_{3}=a_{5}=a_{6}=a_{7}=0$, then we get the $W_{7}$-curvature tensor defined as

$$
\begin{equation*}
W_{7}=R\left(X_{1}, X_{2}\right) X_{3}-\frac{1}{2 m}\left[S\left(X_{2}, X_{3}\right) X_{1}-g\left(X_{2}, X_{3}\right) Q X_{1}\right] . \tag{11}
\end{equation*}
$$

For the $(2 m+1)$-dimensional $\tilde{M}(c)$ Lorentz Sasakian space form, if we choose $X_{1}=\xi, X_{2}=\xi$ and $X_{3}=\xi$ respectively in (11) from (3), (4), (5), the following relations are obtained.

$$
\begin{align*}
& W_{7}\left(\xi, X_{2}\right) X_{3}=\frac{(c+1)-(m+2) c-(5 m+2)}{4 m} g\left(X_{1}, X_{3}\right) \xi \\
& -\eta\left(X_{3}\right) X_{2}-\frac{(c+1)(m+1)}{4 m} \eta\left(X_{2}\right) \eta\left(X_{3}\right) \xi, \tag{12}
\end{align*}
$$

$$
\begin{align*}
& W_{7}\left(X_{1}, \xi\right) X_{3}=\frac{(c+1)-(m+2) c+(3 m-2)}{4 m} \eta\left(X_{3}\right) X_{1} \\
& +g\left(X_{1}, X_{3}\right) \xi+\frac{(c+1)(m+1)}{4 m} \eta\left(X_{3}\right) \eta\left(X_{1}\right) \xi,  \tag{13}\\
& W_{7}\left(X_{1}, X_{2}\right) \xi=\frac{(c+1)-(m+2) c+(3 m-2)}{4 m} \eta\left(X_{2}\right) X_{1} \\
& -\eta\left(X_{1}\right) X_{2}+\frac{(c+1)(m+1)}{4 m} \eta\left(X_{1}\right) \eta\left(X_{2}\right) \xi . \tag{14}
\end{align*}
$$

## 3 Invariant Pseudoparalel Submanifolds of LorentzSasakian Space Forms

Now let's first characterize the pseudoparallel submanifold of the ( $2 m+$ 1)-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$ on the $W_{7}$-curvature tensor.

Definition 3.1. Let $M$ be the invariant submanifold of the $(2 m+$ 1) -dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. If $W_{7} \cdot h$ and $Q(g, h)$ are linearly dependent, $M$ is called $W_{7}$-pseudoparallel submanifold.

Equivalent to this definition, it can be said that there is a function $L_{1}$ on the set $M_{1}=\left\{X_{1} \in M \mid h\left(X_{1}\right) \neq g\left(X_{1}\right)\right\}$ such that

$$
W_{7} \cdot h=L_{1} Q(g, h) .
$$

If $L_{1}=0$ specifically, $M$ is called a $W_{7}$-semiparallel submanifold.
Let us now examine the case of $W_{7}$-pseudoparallel for the submanifold $M$ of the $(2 m+1)$-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$.

Theorem 3.2. Let $M$ be the invariant submanifold of the $(2 m+1)$-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. If $M$ is $W_{7}$-pseudoparallel submanifold, then $M$ is either a total geodesic or

$$
L_{1}=\frac{(m+2) c-(c+1)-(3 m-2)}{4 m}
$$

Proof. Let's assume that $M$ is a $W_{7}$-pseudoparallel submanifold. So, we can write from (9),

$$
\left(W_{7}\left(X_{1}, X_{2}\right) \cdot h\right)\left(X_{4}, X_{5}\right)=L_{1} Q(g, h)\left(X_{4}, X_{5} ; X_{1}, X_{2}\right),
$$

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that is

$$
\begin{align*}
& R^{\perp}\left(X_{1}, X_{2}\right) h\left(X_{4}, X_{5}\right)-h\left(W_{7}\left(X_{1}, X_{2}\right) X_{4}, X_{5}\right) \\
& -h\left(X_{4}, W_{7}\left(X_{1}, X_{2}\right) X_{5}\right)=-L_{1}\left\{h\left(\left(X_{1} \wedge_{g} X_{2}\right) X_{4}, X_{5}\right)\right.  \tag{15}\\
& \left.+h\left(X_{4},\left(X_{1} \wedge_{g} X_{2}\right) X_{5}\right)\right\},
\end{align*}
$$

for all $X_{1}, X_{2}, X_{4}, X_{5} \in \Gamma(T M)$. If we choose $X_{5}=\xi$ in (15) and make use of (5), (14), we get

$$
\begin{align*}
& \left(\frac{(c+1)-(m+2) c+(3 m-2)}{4 m}+L_{1}\right)\left\{\eta\left(X_{2}\right) h\left(X_{4}, X_{1}\right)\right.  \tag{16}\\
& \left.-\eta\left(X_{1}\right) h\left(X_{4}, X_{2}\right)\right\}=0 .
\end{align*}
$$

If we choose $X_{2}=\xi$ in (16), we obtain

$$
\left(\frac{(c+1)-(m+2) c+(3 m-2)}{4 m}+L_{1}\right) h\left(X_{4}, X_{1}\right)=0 .
$$

This completes the proof.
Proposition 3.3. Let $M$ be the invariant submanifold of the $(2 m+$ 1)-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. If $M$ is $W_{7}$-semiparallel submanifold, then $M$ is either a total geodesic or a real space form with constant section curvature $c=\frac{3 m-1}{m+1}$.

Let us now examine the case of $W_{7}-2$ pseudoparallel for the submanifold $M$ of the $(2 m+1)$-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$.
Definition 3.4. Let $M$ be the invariant submanifold of the $(2 m+$ 1)-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. If $W_{7} \cdot \tilde{\nabla} h$ and $Q(g, \tilde{\nabla} h)$ are linearly dependent, $M$ is called $W_{7} 2-$ pseudoparallel submanifold.

Equivalent to this definition, it can be said that there is a function $L_{2}$ on the set $M_{2}=\left\{X_{1} \in M \mid \tilde{\nabla} h\left(X_{1}\right) \neq g\left(X_{1}\right)\right\}$ such that

$$
W_{7} \cdot \tilde{\nabla} h=L_{2} Q(g, \tilde{\nabla} h) .
$$

If $L_{2}=0$ specifically, $M$ is called a $W_{7} 2-$ seniparallel submanifold.
Theorem 3.5. Let $M$ be the invariant submanifold of the $(2 m+1)$-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. If $M$ is $W_{7}-2$ pseudoparallel submanifold, then $M$ is either a total geodesic submanifold or $L_{2}=-1$.

Proof. Let's assume that $M$ is a $W_{7} 2-$ pseudoparallel submanifold. So, we can write from (9),

$$
\begin{equation*}
\left(W_{7}\left(X_{1}, X_{2}\right) \cdot \tilde{\nabla} h\right)\left(X_{4}, X_{5}, X_{3}\right)=L_{2} Q(g, \tilde{\nabla} h)\left(X_{4}, X_{5}, X_{3} ; X_{1}, X_{2}\right), \tag{17}
\end{equation*}
$$

for all $X_{1}, X_{2}, X_{4}, X_{5}, X_{3} \in \Gamma(T M)$. If we choose $X_{1}=X_{3}=\xi$ in (17), we can write

$$
\begin{align*}
& R^{\perp}\left(\xi, X_{2}\right)\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{5}, \xi\right)-\left(\tilde{\nabla}_{W_{7}\left(\xi, X_{2}\right) X_{4}} h\right)\left(X_{5}, \xi\right) \\
& -\left(\tilde{\nabla}_{X_{4}} h\right)\left(W_{7}\left(\xi, X_{2}\right) X_{5}, \xi\right)-\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{5}, W_{7}\left(\xi, X_{2}\right) \xi\right) \\
& =-L_{2}\left\{\left(\tilde{\nabla}_{\left(\xi \wedge_{g} X_{2}\right) X_{4}} h\right)\left(X_{5}, \xi\right)+\left(\tilde{\nabla}_{X_{4}} h\right)\left(\left(\xi \wedge_{g} X_{2}\right) X_{5}, \xi\right)\right.  \tag{18}\\
& \left.+\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{5},\left(\xi \wedge_{g} X_{2}\right) \xi\right)\right\} .
\end{align*}
$$

Let's calculate all the expressions in (18). So, we can write from (1), (5), (8), (12), (13), (14),

$$
\begin{align*}
& \quad R^{\perp}\left(\xi, X_{2}\right)\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{5}, \xi\right)=W_{7}^{\perp}\left(\xi, X_{2}\right)\left\{\nabla_{X_{4}}^{\perp} h\left(X_{5}, \xi\right)\right. \\
& \left.\quad-h\left(\nabla X_{4} X_{5}, \xi\right)-h\left(X_{5}, \nabla X_{4} \xi\right)\right\}  \tag{19}\\
& \quad=R^{\perp}\left(\xi, X_{2}\right) \phi h\left(X_{5}, X_{4}\right), \\
& \left(\tilde{\nabla}_{W_{7}\left(\xi, X_{2}\right) X_{4}} h\right)\left(X_{5}, \xi\right)=\nabla_{W_{7}\left(\xi, X_{2}\right) X_{4}}^{\perp} h\left(X_{5}, \xi\right)-h\left(\nabla W_{7}\left(\xi, X_{2}\right) X_{4} X_{5}, \xi\right) \\
& -h\left(X_{5}, \nabla W_{7}\left(\xi, X_{2}\right) X_{4} \xi\right) \\
& =  \tag{20}\\
& \eta\left(X_{4}\right) \phi h\left(X_{5}, X_{2}\right),
\end{align*}
$$

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$$
\begin{align*}
& \left(\tilde{\nabla} X_{4} h\right)\left(W_{7}\left(\xi, X_{2}\right) X_{5}, \xi\right)=\nabla_{X_{4}}^{\perp} h\left(W_{7}\left(\xi, X_{2}\right) X_{5}, \xi\right) \\
& -h\left(\nabla X_{4} W_{7}\left(\xi, X_{2}\right) X_{5}, \xi\right)-h\left(W_{7}\left(\xi, X_{2}\right) X_{5}, \nabla X_{4} \xi\right)  \tag{21}\\
& =-\eta\left(X_{5}\right) \phi h\left(X_{2}, X_{4}\right),
\end{align*}
$$

$$
\begin{aligned}
& \left(\tilde{\nabla}_{X_{4}} h\right)\left(\left(\xi \wedge_{g} X_{2}\right) X_{5}, \xi\right)=\nabla \frac{\perp}{X_{4}} h\left(\left(\xi \wedge_{g} X_{2}\right) X_{5}, \xi\right) \\
& -h\left(\nabla X_{4}\left(\xi \wedge_{g} X_{2}\right) X_{5}, \xi\right)-h\left(\left(\xi \wedge_{g} X_{2}\right) X_{5}, \nabla X_{4} \xi\right) \\
& =\eta\left(X_{5}\right) \phi h\left(X_{2}, X_{4}\right),
\end{aligned}
$$

$$
\begin{align*}
& \left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{5},\left(\xi \wedge_{g} X_{2}\right) \xi\right)=\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{5},-\eta\left(X_{2}\right) \xi+X_{2}\right) \\
& =-\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{5}, \eta\left(X_{2}\right) \xi\right)+\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{5}, X_{2}\right)  \tag{25}\\
& =-\eta\left(X_{2}\right) \phi h\left(X_{5}, X_{4}\right)+\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{5}, X_{2}\right) .
\end{align*}
$$

If we substitute (19), (20), (21), (22), (23), (24), (25) for (18), we obtain

$$
\begin{align*}
& R^{\perp}\left(\xi, X_{2}\right) \phi h\left(X_{5}, X_{4}\right)-\eta\left(X_{4}\right) \phi h\left(X_{5}, X_{2}\right)+\eta\left(X_{5}\right) \phi h\left(X_{2}, X_{4}\right) \\
& -\eta\left(X_{2}\right) \phi h\left(X_{5}, X_{4}\right)+\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{5}, X_{2}\right) \\
& =-L_{2}\left\{\eta\left(X_{4}\right) \phi h\left(X_{5}, X_{2}\right)+\eta\left(X_{5}\right) \phi h\left(X_{2}, X_{4}\right)\right. \\
& \left.-\eta\left(X_{2}\right) \phi h\left(X_{5}, X_{4}\right)-\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{5}, X_{2}\right)\right\} . \tag{26}
\end{align*}
$$

If we choose $X_{5}=\xi$ in (26) from (10), we get

$$
\begin{align*}
& \phi h\left(X_{2}, X_{4}\right)+\left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi, X_{2}\right)=-L_{2}\left\{\phi h\left(X_{2}, X_{4}\right)\right.  \tag{27}\\
& \left.+\left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi, X_{2}\right)\right\} .
\end{align*}
$$

On the other hand, it is clear that

$$
\begin{equation*}
\left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi, X_{2}\right)=\phi h\left(X_{2}, X_{4}\right) . \tag{28}
\end{equation*}
$$

If (28) is written instead of (27), we obtain

$$
\left(1+L_{2}\right) h\left(X_{2}, X_{4}\right)=0 .
$$

This completes the proof.
Proposition 3.6. Let $M$ be the invariant submanifold of the $(2 m+$ 1)-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. Then $M$ is $W_{7}-2$ semiparallel submanifold if and only if $M$ is totally geodesic.

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Let us now examine the case of $W_{7}-$ Ricci generalized pseudoparallel for the submanifold $M$ of the $(2 m+1)$-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$.

Definition 3.7. Let $M$ be the invariant submanifold of the $(2 m+$ 1) - dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. If $W_{7} \cdot h$ and $Q(S, h)$ are linearly dependent, $M$ is called $W_{7}$-Ricci generalized pseudoparallel submanifold.

Equivalent to this definition, it can be said that there is a function $L_{3}$ on the set $M_{3}=\left\{X_{1} \in M \mid h\left(X_{1}\right) \neq S\left(X_{1}\right)\right\}$ such that

$$
W_{7} \cdot h=L_{3} Q(S, h) .
$$

If $L_{3}=0$ specifically, $M$ is called a $W_{7}$-Ricci generalized semiparallel submanifold.

Theorem 3.8. Let $M$ be the invariant submanifold of the ( $2 m+1$ )-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. If $M$ is $W_{7}-$ Ricci generalized pseudoparallel submanifold, then $M$ is either a total geodesic or $L_{3}=\frac{2}{4 m-(c+1)}$ provided $4 m \neq(c+1)$.

Proof. Let's assume that $M$ is a $W_{7}$-Ricci generalized pseudoparallel submanifold. So, we can write from (9),

$$
\left(W_{7}\left(X_{1}, X_{2}\right) \cdot h\right)\left(X_{4}, X_{5}\right)=L_{3} Q(S, h)\left(X_{4}, X_{5} ; X_{1}, X_{2}\right),
$$

that is

$$
\begin{align*}
& R^{\perp}\left(X_{1}, X_{2}\right) h\left(X_{4}, X_{5}\right)-h\left(W_{7}\left(X_{1}, X_{2}\right) X_{4}, X_{5}\right) \\
& -h\left(X_{4}, W_{7}\left(X_{1}, X_{2}\right) X_{5}\right)=-\lambda_{3}\left\{h\left(\left(X_{1} \wedge_{g} X_{2}\right) X_{4}, X_{5}\right)\right.  \tag{29}\\
& \left.+h\left(X_{4},\left(X_{1} \wedge_{g} X_{2}\right) X_{5}\right)\right\},
\end{align*}
$$

for all $X_{1}, X_{2}, X_{4}, X_{5} \in \Gamma(T M)$. If we choose $X_{1}=X_{5}=\xi$ in (29) and make use of (10), (12), we get

$$
\left[1+\frac{(c+1)-4 m}{2} L_{3}\right] h\left(X_{4}, X_{2}\right)=0 .
$$

It is clear from the last equation that either

$$
h\left(X_{4}, X_{2}\right)=0,
$$

or

$$
L_{3}=\frac{2}{4 m-(c+1)} .
$$

This completes the proof.
Proposition 3.9. Let $M$ be the invariant submanifold of the $(2 m+$ $1)$ - dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. Then $M$ is $W_{7}-$ Ricci generalized semiparallel submanifold if and only if $M$ is totally geodesic.

Let us now examine the case of $W_{7} 2-$ Ricci generalized pseudoparallel for the submanifold $M$ of the $(2 m+1)$-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$.
Definition 3.10. Let $M$ be the invariant submanifold of the $(2 m+$ 1)-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. If $W_{7} \cdot \tilde{\nabla} h$ and $Q(S, \tilde{\nabla} h)$ are linearly dependent, $M$ is called $W_{7} 2-$ Ricci generalized pseudoparallel submanifold.

Equivalent to this definition, it can be said that there is a function $L_{4}$ on the set $M_{4}=\left\{X_{1} \in M \mid \tilde{\nabla} h\left(X_{1}\right) \neq S\left(X_{1}\right)\right\}$ such that

$$
W_{7} \cdot \tilde{\nabla} h=L_{4} Q(S, \tilde{\nabla} h)
$$

If $L_{4}=0$ specifically, $M$ is called a $W_{7} 2-$ Ricci generalized semiparallel submanifold.
Theorem 3.11. Let $M$ be the invariant submanifold of the $(2 m+$ 1)-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. If $M$ is $W_{7}-2$ Ricci generalized pseudoparallel submanifold, then $M$ is either a total geodesic or $L_{4}=\frac{2}{4 m-(c+1)}$ provided $4 m \neq(c+1)$.
Proof. Let's assume that $M$ is a $W_{7} 2-$ Ricci generalized pseudoparallel submanifold. So, we can write

$$
\begin{equation*}
\left(W_{7}\left(X_{1}, X_{2}\right) \cdot \tilde{\nabla} h\right)\left(X_{4}, X_{5}, X_{3}\right)=L_{4} Q(S, \tilde{\nabla} h)\left(X_{4}, X_{5}, X_{3} ; X_{1}, X_{2}\right), \tag{30}
\end{equation*}
$$

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for all $X_{1}, X_{2}, X_{4}, X_{5}, X_{3} \in \Gamma(T M)$. If we choose $X_{1}=X_{5}=\xi$ in (30), we can write

$$
\begin{align*}
& R^{\perp}\left(\xi, X_{2}\right)\left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi, X_{3}\right)-\left(\tilde{\nabla}_{W_{7}\left(\xi, X_{2}\right) X_{4}} h\right)\left(\xi, X_{3}\right) \\
& -\left(\tilde{\nabla}_{X_{4}} h\right)\left(W_{7}\left(\xi, X_{2}\right) \xi, X_{3}\right)-\left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi, W_{7}\left(\xi, X_{2}\right) X_{3}\right)  \tag{31}\\
& =-L_{4}\left\{\left(\tilde{\nabla}_{\left(\xi \wedge_{S} X_{2}\right) X_{4}} h\right)\left(\xi, X_{3}\right)+\left(\tilde{\nabla}_{X_{4}} h\right)\left(\left(\xi \wedge_{S} X_{2}\right) \xi, X_{3}\right)\right. \\
& \left.+\left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi,\left(\xi \wedge_{S} X_{2}\right) X_{3}\right)\right\} .
\end{align*}
$$

Let's calculate all the expressions in (31). So, we can write from (1), (6), (8), (12), (13), (14),

$$
\begin{align*}
& R^{\perp}\left(\xi, X_{2}\right)\left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi, X_{3}\right)=W_{7}^{\perp}\left(\xi, X_{2}\right)\left\{\nabla_{X_{4}}^{\perp} h\left(\xi, X_{3}\right)\right. \\
& \left.-h\left(\nabla X_{4} X_{3}, \xi\right)-h\left(X_{3}, \nabla X_{4} \xi\right)\right\}  \tag{32}\\
& =R^{\perp}\left(\xi, X_{2}\right) \phi h\left(X_{3}, X_{4}\right), \\
& \left(\tilde{\nabla}_{W_{7}\left(\xi, X_{2}\right) X_{4}} h\right)\left(\xi, X_{3}\right)=\nabla_{W_{7}\left(\xi, X_{2}\right) X_{4}}^{\perp} h\left(\xi, X_{3}\right)-h\left(\nabla_{W_{7}\left(\xi, X_{2}\right) X_{4}} \xi, X_{3}\right) \\
& -h\left(\xi, \nabla W_{7}\left(\xi, X_{2}\right) X_{4} X_{3}\right) \\
& =-\eta\left(X_{4}\right) \phi h\left(X_{2}, X_{3}\right) \text {, }  \tag{33}\\
& \left(\tilde{\nabla}_{X_{4}} h\right)\left(W_{7}\left(\xi, X_{2}\right) \xi, X_{3}\right)=\left(\tilde{\nabla}_{X_{4}} h\right)\left(\eta\left(X_{2}\right) \xi-X_{2}, X_{3}\right) \\
& =\nabla{ }_{X_{4}}^{\perp} h\left(\eta\left(X_{2}\right) \xi, X_{3}\right)-h\left(\nabla X_{4} \eta\left(X_{2}\right) \xi, X_{3}\right)  \tag{34}\\
& -h\left(\eta\left(X_{2}\right) \xi, \nabla X_{4} X_{3}\right)-\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{2}, X_{3}\right) \\
& =\eta\left(X_{2}\right) \phi h\left(X_{4}, X_{3}\right)-\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{2}, X_{3}\right),
\end{align*}
$$

$$
\begin{align*}
& \left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi, W_{7}\left(\xi, X_{2}\right) X_{3}\right)=\nabla{ }_{X_{4}}^{\perp} h\left(\xi, W_{7}\left(\xi, X_{2}\right) X_{3}\right) \\
& -h\left(\nabla X_{4} \xi, W_{7}\left(\xi, X_{2}\right) X_{3}\right)-h\left(\xi, \nabla X_{4} W_{7}\left(\xi, X_{2}\right) X_{3}\right)  \tag{35}\\
& =-\eta\left(X_{3}\right) \phi h\left(X_{4}, X_{2}\right) \\
& \left(\tilde{\nabla}_{\left(\xi \wedge_{S} X_{2}\right) X_{4}} h\right)\left(\xi, X_{3}\right)=\nabla \stackrel{\perp}{\left(\xi \wedge_{S} X_{2}\right) X_{4}} h h\left(\xi, X_{3}\right)-h\left(\nabla\left(\xi \wedge_{S} X_{2}\right) X_{4} \xi, X_{3}\right) \\
& -h\left(\xi, \nabla\left(\xi \wedge_{S} X_{2}\right) X_{4} X_{3}\right) \\
& =\frac{(c+1)-4 m}{2} \eta\left(X_{4}\right) \phi h\left(X_{2}, X_{3}\right),  \tag{36}\\
& \left(\tilde{\nabla}_{X_{4}} h\right)\left(\left(\xi \wedge_{S} X_{2}\right) \xi, X_{3}\right)=\left(\tilde{\nabla}_{X_{4}} h\right)\left(S\left(X_{2}, \xi\right) \xi-S(\xi, \xi) X_{2}, X_{3}\right) \\
& =\frac{(c+1)-4 m}{2}\left\{\left(\tilde{\nabla}_{X_{4}} h\right)\left(-\eta\left(X_{2}\right) \xi+X_{2}, X_{3}\right)\right\} \\
& =\frac{(c+1)-4 m}{2}\left\{-\nabla{ }^{\perp}{ }_{4} h\left(\eta\left(X_{2}\right) \xi, X_{3}\right)+h\left(\nabla X_{4} \eta\left(X_{2}\right) \xi, X_{3}\right)\right. \\
& \left.+h\left(\eta\left(X_{2}\right) \xi, \nabla X_{4} X_{3}\right)+\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{2}, X_{3}\right)\right\} \\
& =\frac{(c+1)-4 m}{2}\left\{\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{2}, X_{3}\right)-\eta\left(X_{2}\right) \phi h\left(X_{4}, X_{3}\right)\right\},  \tag{37}\\
& \left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi,\left(\xi \wedge_{S} X_{2}\right) X_{3}\right)=\left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi, S\left(X_{2}, X_{3}\right) \xi-S\left(\xi, X_{3}\right) X_{2}\right) \\
& =\left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi, S\left(X_{2}, X_{3}\right) \xi\right)+\frac{(c+1)-4 m}{2}\left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi, \eta\left(X_{3}\right), X_{2}\right) \\
& =\frac{(c+1)-4 m}{2} \eta\left(X_{3}\right) \phi h\left(X_{4}, X_{2}\right) . \tag{38}
\end{align*}
$$

If we substitute (32), (33), (34), (35), (36), (37), (38) for (31), we obtain

$$
\begin{align*}
& R^{\perp}\left(\xi, X_{2}\right) \phi h\left(X_{3}, X_{4}\right)+\eta\left(X_{4}\right) \phi h\left(X_{2}, X_{3}\right)-\eta\left(X_{2}\right) \phi h\left(X_{4}, X_{3}\right) \\
& +\eta\left(X_{3}\right) \phi h\left(X_{4}, X_{2}\right)+\left(\tilde{\nabla} X_{4} h\right)\left(X_{2}, X_{3}\right) \\
& =-L_{4}\left\{\frac{(c+1)-4 m}{2} \eta\left(X_{4}\right) \phi h\left(X_{2}, X_{3}\right)\right. \\
& -\frac{(c+1)-4 m}{2} \eta\left(X_{2}\right) \phi h\left(X_{4}, X_{3}\right)+\frac{(c+1)-4 m}{2} \eta\left(X_{3}\right) \phi h\left(X_{4}, X_{2}\right) \\
& \left.+\frac{(c+1)-4 m}{2}\left(\tilde{\nabla} X_{4} h\right)\left(X_{2}, X_{3}\right)\right\} . \tag{39}
\end{align*}
$$

If we choose $X_{3}=\xi$ in (39), we get

$$
\begin{align*}
& \left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{2}, \xi\right)+\phi h\left(X_{4}, X_{2}\right)=-\frac{(c+1)-4 m}{2} L_{4}\left\{\left(\tilde{\nabla}_{X_{4}} h\right)\left(X_{2}, \xi\right)\right. \\
& \left.+\phi h\left(X_{4}, X_{2}\right)\right\} . \tag{40}
\end{align*}
$$

On the other hand, it is clear that

$$
\begin{equation*}
\left(\tilde{\nabla}_{X_{4}} h\right)\left(\xi, X_{2}\right)=\phi h\left(X_{2}, X_{4}\right) . \tag{41}
\end{equation*}
$$

If (41) is written instead of (40), we obtain

$$
2 \phi h\left(X_{2}, X_{4}\right)=[4 m-(c+1)] L_{4} \phi h\left(X_{2}, X_{4}\right) .
$$

It is clear from the last equality

$$
h\left(X_{2}, X_{4}\right)=0 \text { or } L_{4}=\frac{2}{4 m-(c+1)} .
$$

This completes the proof.
Proposition 3.12. Let $M$ be the invariant submanifold of the $(2 m+$ 1)-dimensional Lorentz-Sasakian space form $\tilde{M}(c)$. Then $M$ is $W_{7}$ 2-Ricci generalized semiparallel submanifold if and only if $M$ is totally geodesic.

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