

Journal of Mathematical Extension
Vol. 17, No. 1, (2023) (8)1-17
URL: <https://doi.org/10.30495/JME.2023.2468>
ISSN: 1735-8299
Original Research Paper

On Deformable Implicit Fractional Differential Equations in b -Metric Spaces

A. Salim*

Hassiba Benbouali University of Chlef

S. Krim

Djillali Liabes University of Sidi Bel-Abbes

S. Abbas

University of Saïda–Dr. Moulay Tahar

M. Benchohra

Djillali Liabes University of Sidi Bel-Abbes

Abstract. In this paper, we prove some existence and uniqueness results for some classes of deformable implicit fractional differential equations in b -Metric spaces with initial conditions. We base our arguments on some some fixed point theorems. Finally, we provide an example to illustrate our results.

AMS Subject Classification: 26A33; 34A08; 34K37.

Keywords and Phrases: Fixed point, implicit differential equations, existence, uniqueness, deformable fractional derivative, nonlocal conditions.

1 Introduction

Recently, fractional differential equations have been used in engineering, mathematics, physics, and other applied disciplines. The existence

Received: August 2022; Accepted: January 2023

*Corresponding Author

of solutions to the ordinary and fractional differential equations with various conditions has received much attention; see the monographs [1, 2, 3, 22, 23, 24] and the papers [21, 19, 13, 12, 8, 7]. Several results of implicit fractional differential equations have been recently provided, see [1, 20, 15], and the references therein.

In [10, 11], Czerwik introduced the concept of b -metric. Following these early studies, numerous problems with differential equations in b -metric spaces has been intensively researched; see [9, 5, 6, 14] as well as the included references.

In [25], Zulfeqarr *et al.* proposed the novel notion of deformable fractional derivative, employing the limit technique as in the usual derivative. It was termed "deformable" due to its inherent ability of continuously deforming function to derivative. Deformable derivatives can be thought of as fractional order derivatives.

The authors of [16] investigated further properties of the new concept of deformable derivative and used the results to study the following Cauchy problem with non-local condition:

$$\begin{aligned}\mathfrak{D}_0^\alpha x(t) &= f(t, x(t)), \quad t \in (0, T], \\ x(0) + g(x) &= x_0,\end{aligned}$$

where \mathfrak{D}_0^α is the deformable derivative of order $\alpha \in (0, 1)$, and $g : \mathcal{C} \rightarrow \mathbb{R}$ is a continuous function. Their arguments are based on Krasnoselskii's fixed point theorem.

In [18], Meraj and Pandey studied the existence and uniqueness of mild solution for the following initial value problem:

$$\begin{aligned}\mathfrak{D}_0^\alpha x(t) &= Ax(t) + f(t, x(t)), \quad t \in J, \\ x(0) &= x_0,\end{aligned}$$

where $A : D(A) \subset X \rightarrow X$ is an infinitesimal generator of a C_0 -semigroup $T(t)(t \geq 0)$ on a suitable space $X, x_0 \in X$, and $J = [0, b], b > 0$ is a constant. The results are obtained with the help of semigroup theory, Banach fixed point theorem, and Schauder fixed point theorem.

In [17], by using Weissinger's and Krasnoselskii's fixed point theorems, Mebrat and N'Guérékata studied the existence of solutions for the following problem:

$$\begin{aligned}\mathfrak{D}_0^\alpha \chi(\theta) &= \Phi(\chi(\theta)) + \Psi(\theta, \chi(\theta)) + \int_0^\theta \Upsilon(\theta, s, \chi(s)) ds, \quad \theta \in \Theta, \\ \chi(0) &= \chi_0,\end{aligned}$$

where $\Psi : \Theta \times E \rightarrow E, \Upsilon : \Theta \times \Theta \times E \rightarrow E$ are continuous functions.

Motivated by the above-mentioned papers, first we study the existence and uniqueness of solutions for the implicit problem with nonlinear fractional differential equation involving the deformable fractional derivative:

$$(\mathfrak{D}_0^\alpha \chi)(\theta) = \Psi(\theta, \chi(\theta), \mathfrak{D}_0^\alpha \chi(\theta)); \quad \theta \in \Theta := [0, \kappa], \quad (1)$$

with the initial condition

$$\chi(0) = \chi_0, \quad (2)$$

where $0 < \alpha < 1$, \mathfrak{D}_0^α is the deformable fractional derivative defined in [25], $\Psi : \Theta \times \mathbb{R}^2 \rightarrow \mathbb{R}$ is a given function to be specified later and $\chi_0 \in \mathbb{R}$.

Next, we discuss the existence of solutions for the following problem of deformable implicit nonlocal fractional differential equations:

$$\begin{cases} (\mathfrak{D}_0^\alpha \chi)(\theta) = \Psi(\theta, \chi(\theta), \mathfrak{D}_0^\alpha \chi(\theta)); \quad \theta \in \Theta, \\ \chi(0) + \bar{\psi}(\chi) = \chi_0, \end{cases} \quad (3)$$

where $\bar{\psi} : C(\Theta, \mathbb{R}) \rightarrow \mathbb{R}$ is a continuous function.

2 Preliminaries

First, we give the definitions and the notations that we will use throughout this paper. We denote by $C(\Theta, \mathbb{R})$ the Banach space of all continuous functions from Θ into \mathbb{R} with the following norm

$$\|\chi\|_\infty = \sup_{\theta \in \Theta} \{|\chi(\theta)|\}.$$

Consider the space $X_b^p(0, \kappa)$, ($b \in \mathbb{R}$, $1 \leq p \leq \infty$) of those complex-valued Lebesgue measurable functions Ψ on $[0, \kappa]$ for which $\|\Psi\|_{X_b^p} < \infty$, where the norm is given by:

$$\|\Psi\|_{X_b^p} = \left(\int_0^\kappa |\theta^b \Psi(\theta)|^p \frac{d\theta}{\theta} \right)^{\frac{1}{p}}, \quad (1 \leq p < \infty, b \in \mathbb{R}).$$

Definition 2.1 (The deformable fractional derivative [16, 25]). Let $\Psi : [0, +\infty) \rightarrow \mathbb{R}$ be a given function, then the non-conformable fractional derivative of Ψ of order α is defined by

$$(\mathfrak{D}_0^\alpha \Psi)(\theta) = \lim_{\varepsilon \rightarrow 0} \frac{(1 + \varepsilon\beta)\Psi(\theta + \varepsilon\alpha) - \Psi(\theta)}{\varepsilon},$$

where $\alpha + \beta = 1$ and $\alpha \in (0, 1]$. If the deformable fractional derivative of Ψ of order α exists, then we simply say that Ψ is α -differentiable.

Definition 2.2 (The α -fractional integral [16, 17]). For $\alpha \in (0, 1]$ and a continuous function Ψ , let

$$(\mathcal{J}_{0+}^\alpha \Psi)(\theta) = \frac{1}{\alpha} e^{-\frac{\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Psi(\tau) d\tau.$$

Lemma 2.3 ([16, 17]). *If $\alpha, \alpha_1 \in (0, 1]$ such that $\alpha + \beta = 1$, Ψ and Φ are two α -differentiable functions at a point θ and m, n are two given numbers, then the improved conformable fractional derivative satisfies the following properties:*

- $\mathfrak{D}_0^\alpha(\lambda) = \beta\lambda$, for any constant λ ;
- $\mathfrak{D}_0^\alpha(m\Psi + n\Phi) = m\mathfrak{D}_0^\alpha(\Psi) + n\mathfrak{D}_0^\alpha(\Phi)$;
- $\mathfrak{D}_0^\alpha(\Psi\Phi) = \Phi\mathfrak{D}_0^\alpha(\Psi) + \alpha\Psi\Phi'$;
- $\mathcal{J}_{0+}^\alpha \mathcal{J}_{0+}^{\alpha_1} \Psi = \mathcal{J}_{0+}^{\alpha+\alpha_1} \Psi$.

Lemma 2.4 ([16, 17]). *If $\alpha \in (0, 1]$, f is continuous function, then we have:*

- $(\mathcal{J}_{0+}^\alpha \mathfrak{D}_0^\alpha(\Psi))(\theta) = \Psi(\theta) - e^{-\frac{\beta}{\alpha}\theta} \Psi(0)$;
- $\mathfrak{D}_0^\alpha(\mathcal{J}_{0+}^\alpha \Psi)(\theta) = \Psi(\theta)$.

Lemma 2.5. *Let $\Phi \in L^1(\Theta)$ and $0 < \alpha \leq 1$. Then the initial value problem*

$$\begin{cases} (\mathfrak{D}_0^\alpha \chi)(\theta) = \Phi(\theta); \theta \in \Theta := [0, \kappa], \\ \chi(0) = \chi_0, \end{cases} \quad (4)$$

has a unique solution defined by

$$\chi(\theta) = \chi_0 e^{\frac{-\beta}{\alpha}\theta} + \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi(\tau) d\tau. \quad (5)$$

Proof. Applying the α -fractional integral of order α to both sides the equation

$$(\mathfrak{D}_0^\alpha \chi)(\theta) = \Phi(\theta),$$

and by using Lemma 2.4 and if $\theta \in \Theta$, we get

$$\chi(\theta) - \chi(0) e^{\frac{-\beta}{\alpha}\theta} = \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi(\tau) d\tau. \quad (6)$$

From the initial conditions, we get

$$\chi(\theta) = \chi_0 e^{\frac{-\beta}{\alpha}\theta} + \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi(\tau) d\tau \quad (7)$$

Conversely, we can easily show by Lemma 2.3 that if χ verifies equation (5) then it satisfied the problem (4). \square

Definition 2.6 ([5]). Let \mathcal{H} be a set and $\varepsilon \geq 1$ be a given real number. A distance function $\delta : \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{R}_+^*$ is called a b -metric if the following conditions hold for all $\xi_1, \xi_2, \xi_3 \in \mathcal{H}$:

- (1) $\delta(\xi_1, \xi_2) = 0$ if and only if $\xi_1 = \xi_2$,
- (2) $\delta(\xi_1, \xi_2) = \delta(\xi_2, \xi_1)$,
- (3) $\delta(\xi_1, \xi_2) \leq \varepsilon[\delta(\xi_1, \xi_3) + \delta(\xi_3, \xi_2)]$.

Then, the pair $(\mathcal{H}, \delta, \varepsilon)$ is called a b -metric space with parameter ε .

Consider $\tilde{\Xi}$ the set of continuous and increasing function $\psi : \mathbb{R}_+^* \rightarrow \mathbb{R}_+^*$ satisfying the property: $\psi(\varepsilon\chi) \leq \varepsilon\psi(\chi) \leq \varepsilon\chi$, for $\varepsilon > 1$ and $\psi(0) = 0$. We denote by Ξ the family of all nondecreasing functions $\eta : \mathbb{R}_+^* \rightarrow [0, \frac{1}{\varepsilon^2})$ for some $\varepsilon \geq 1$.

Definition 2.7 ([5]). Let $(\mathcal{H}, \delta, \varepsilon)$ be a b -metric space, $\mathfrak{S} : \mathcal{H} \rightarrow \mathcal{H}$ is said to be a generalized ω - ψ -Geraghty mapping whenever there exists $\omega : \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{R}_+^*$ such that

$$\omega(\xi_1, \xi_2)\psi(\varepsilon^3 d(\mathfrak{S}(\xi_1), \mathfrak{S}(\xi_2))) \leq \eta(\psi(\delta(\xi_1, \xi_2)))\psi(\delta(\xi_1, \xi_2)),$$

for $\xi_1, \xi_2 \in \mathcal{H}$, where $\eta \in \Xi$.

Definition 2.8 ([5]). Let \mathcal{H} be a non empty set, $\mathfrak{S} : \mathcal{H} \rightarrow \mathcal{H}$ and $\omega : \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{R}_+^*$ be given mappings. The operator \mathfrak{S} is orbital ω -admissible if for $\chi \in \mathcal{H}$, we have

$$\omega(\chi, \mathfrak{S}(\chi)) \geq 1 \Rightarrow \omega(\mathfrak{S}(\chi), \mathfrak{S}^2(\chi)) \geq 1.$$

Theorem 2.9 ([5]). Let (\mathcal{H}, δ) be a complete b -metric space and $\mathfrak{N} : \mathcal{H} \rightarrow \mathcal{H}$ be a generalized ω - ψ -Geraghty mapping where

- (a) \mathfrak{N} is ω -admissible;
- (b) there exists $\chi_0 \in \mathcal{H}$ where $\omega(\chi_0, \mathfrak{N}(\chi_0)) \geq 1$;
- (c) If $(\chi_n)_{n \in \mathbb{N}} \subset \mathcal{H}$ with $\chi_n \rightarrow \chi$ and $\omega(\chi_n, \chi_{n+1}) \geq 1$, then $\omega(\chi_n, \chi) \geq 1$,

Then \mathfrak{N} admit a fixed point. Further, if

- (d) for all fixed points χ, χ' of \mathfrak{N} , either

$$\omega(\chi, \chi') \geq 1 \text{ or } \omega(\chi', \chi) \geq 1,$$

Then \mathfrak{N} admit a unique fixed point.

3 Existence of Solutions for the First Problem

Let $(C(\Theta), \delta, 2)$ be the complete b -metric space with $\varepsilon = 2$, where $\delta : C(\Theta) \times C(\Theta) \rightarrow \mathbb{R}_+^*$, is given by:

$$\delta(\chi, \mathfrak{S}) = \|(\chi - \mathfrak{S})^2\|_\infty := \sup_{\theta \in \Theta} |\chi(\theta) - \mathfrak{S}(\theta)|^2.$$

In this section, we establish some existence results for problem (1)-(2).

Definition 3.1. By a solution of problem (1)-(2), we mean a continuous function $\chi \in C(\Theta)$ given by

$$\chi(\theta) = \chi_0 e^{\frac{-\beta}{\alpha}\theta} + \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi(\tau) d\tau, \quad (8)$$

where $\Phi \in C(\Theta)$ such that $\Phi(\theta) = \Psi(\theta, \chi(\theta), \Phi(\theta))$.

The hypotheses:

(H₁) There exist $\gamma_1 : C(\Theta) \times C(\Theta) \rightarrow \mathbb{R}_+^*$ and $\gamma_2 : \Theta \rightarrow (0, 1)$ where for $\chi, \mathfrak{S}, \chi_1, \mathfrak{S}_1 \in C(\Theta)$ and $\theta \in \Theta$, we have

$$|\Psi(\theta, \chi, \mathfrak{S}) - \Psi(\theta, \chi_1, \mathfrak{S}_1)| \leq \gamma_1(\chi, \mathfrak{S}) \|\chi - \mathfrak{S}\|_\infty + \gamma_2(\theta) \|\chi_1 - \mathfrak{S}_1\|_\infty$$

with

$$\left\| \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \frac{\gamma_1(\chi, \mathfrak{S})}{1 - \gamma_2^*} d\tau \right\|_\infty^2 \leq \psi(\|(\chi - \mathfrak{S})^2\|_\infty).$$

(H₂) There exist $\psi \in \tilde{\Xi}$ and $\bar{\lambda}_0 \in C(\Theta)$ and a function $\gamma_3 : C(\Theta) \times C(\Theta) \rightarrow \mathbb{R}$, where

$$\gamma_3 \left(\bar{\lambda}_0(\theta), \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi(\tau) d\tau \right) \geq 0$$

where $\Phi \in C(\Theta)$ such that $\Phi(\theta) = \Psi(\theta, \bar{\lambda}_0(\theta), \Phi(\theta))$.

(H₃) For each $\theta \in \Theta$, and $\chi, \mathfrak{S} \in C(\Theta)$, we have:

$$\gamma_3(\chi(\theta), \mathfrak{S}(\theta)) \geq 0$$

implies

$$\gamma_3 \left(\frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi(\tau) d\tau, \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi'(\tau) d\tau \right) \geq 0,$$

where $\Phi, \Phi' \in C(\Theta)$ such that

$$\Phi(\theta) = \Psi(\theta, \chi(\theta), \Phi(\theta))$$

and

$$\Phi'(\theta) = \Psi(\theta, \mathfrak{S}(\theta), \Phi'(\theta)).$$

(H₄) If $(\chi_n)_{n \in \mathbb{N}} \subset C(\Theta)$ with $\chi_n \rightarrow \chi$ and $\gamma_3(\chi_n, \chi_{n+1}) \geq 1$, then

$$\gamma_3(\chi_n, \chi) \geq 1.$$

(H₅) For all fixed solutions χ, χ' of (1)-(2), either

$$\gamma_3(\chi(\theta), \chi'(\theta)) \geq 0,$$

or

$$\gamma_3(\chi'(\theta), \chi(\theta)) \geq 0.$$

Theorem 3.2. *Assume that the hypotheses (H₁)-(H₄) hold. Then the problem (1)-(2) has at least one solution. And, if (H₅) holds, then the solution is unique.*

Proof. Let $\mathcal{K} : C(\Theta) \rightarrow C(\Theta)$ be the operator given by:

$$(\mathcal{K}\chi)(\theta) = \chi_0 e^{\frac{-\beta}{\alpha}\theta} + \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi(\tau) d\tau, \quad (9)$$

where $\Phi \in C(\Theta)$ such that $\Phi(\theta) = \Psi(\theta, \chi_\theta, \Phi(\theta))$.

The function $\omega : C(\Theta) \times C(\Theta) \rightarrow \mathbb{R}_+^*$ is given by:

$$\begin{cases} \omega(\chi, \chi') = 1; & \text{if } \gamma_3(\chi(\theta), \chi'(\theta)) \geq 0, \theta \in \Theta, \\ \omega(\chi, \chi') = 0; & \text{eles.} \end{cases}$$

First, we demonstrate that \mathcal{K} is a generalized ω - ψ -Geraghty operator: For any $\chi, \chi' \in C(\Theta)$. Then, for each $\theta \in \Theta$, we obtain

$$|(\mathcal{K}\chi)(\theta) - (\mathcal{K}\chi')(\theta)| \leq \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} |\Phi(\vartheta) - \Phi'(\vartheta)| d\vartheta,$$

where $\Phi, \Phi' \in C(\Theta)$ such that

$$\Phi(\theta) = \Psi(\theta, \chi(\theta), \Phi(\theta)) \text{ and } \Phi'(\theta) = \Psi(\theta, \chi'(\theta), \Phi'(\theta)).$$

From (H₁) we have

$$\|\Phi - \Phi'\|_\infty \leq \frac{\gamma_1(\chi, \chi')}{1 - \gamma_2^*} \|(\chi_2 - \chi'_2)^2\|_\infty^{\frac{1}{2}},$$

where $\gamma_2^* = \sup_{\theta \in \Theta} |\gamma_2(\theta)|$.

Next, we have

$$|(\mathcal{K}\chi)(\theta) - (\mathcal{K}\chi')(\theta)| \leq \frac{1}{\alpha} e^{-\frac{\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \frac{\gamma_1(\chi, \chi')}{1 - \gamma_2^*} \|(\chi - \chi')^2\|_\infty^{\frac{1}{2}} d\vartheta.$$

Thus

$$\begin{aligned} & \omega(\varkappa_2, \varkappa'_2) |(\mathcal{K}\varkappa_2)(\theta) - (\mathcal{K}\varkappa'_2)(\theta)|^2 \\ & \leq \|(\chi - \chi')^2\|_\infty \omega(\chi, \chi') \left\| \frac{1}{\alpha} e^{-\frac{\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \frac{\gamma_1(\chi, \chi')}{1 - \gamma_2^*} d\vartheta \right\|_\infty^2 \\ & \leq \|(\chi - \chi')^2\|_\infty \psi(\|(\chi - \chi')^2\|_\infty). \end{aligned}$$

Hence

$$\omega(\chi, \chi') \psi(2^3 d(\mathcal{K}\chi, \mathcal{K}\chi')) \leq \eta(\psi(\delta(\chi, \chi'))) \psi(\delta(\chi, \chi')),$$

where $\eta \in \Xi$, $\psi \in \tilde{\Xi}$, with $\eta(\theta) = \frac{1}{8}\theta$, and $\psi(\theta) = \theta$. So, \mathcal{K} is generalized ω - ψ -Geraghty operator.

Let $\chi, \chi' \in C(\Theta)$ such that

$$\omega(\chi, z\chi') \geq 1.$$

Thus, for each $\theta \in \Theta$, we have

$$\gamma_3(\chi(\theta), \chi'(\theta)) \geq 0.$$

This implies from (H_3) that

$$\gamma_3(\mathcal{K}\chi(\theta), \mathcal{K}\chi'(\theta)) \geq 0,$$

which gives

$$\omega(\mathcal{K}\chi, \mathcal{K}\chi') \geq 1.$$

Hence, \mathcal{K} is a ω -admissible.

Now, by (H_2) , there exist $\bar{\lambda}_0 \in C(\Theta)$ such that

$$\omega(\bar{\lambda}_0, \mathfrak{N}(\bar{\lambda}_0)) \geq 1.$$

Thus, by (H_4) , if $(\bar{\lambda}_n)_{n \in \mathbb{N}} \subset \mathcal{H}$ with $\bar{\lambda}_n \rightarrow \bar{\lambda}$ and $\omega(\bar{\lambda}_n, \bar{\lambda}_{n+1}) \geq 1$, then

$$\omega(\bar{\lambda}_n, \bar{\lambda}) \geq 1.$$

By Theorem 2.9, we conclude that \mathcal{K} has a fixed point χ which is a solution of (1)-(2).

Further, (H_5) implies that if χ and χ' are fixed points of \mathcal{K} , then either

$$\gamma_3(\chi, \chi') \geq 0 \text{ or } \gamma_3(\chi', \chi) \geq 0.$$

Thus

$$\omega(\chi, \chi') \geq 1 \text{ or } \omega(\chi', \chi) \geq 1,$$

Then, (1)-(2) has a unique solution. \square

4 Existence of Solutions for the Second Problem

In this section, we establish some existence results for problem (3).

Let us introduce the following hypotheses:

(H_6) There exist constant $\varsigma > 0$ such that

$$|\bar{\psi}(\chi) - \bar{\psi}(\mathfrak{S})| \leq \varsigma \|\chi - \mathfrak{S}\|_\infty,$$

for each $\chi, \mathfrak{S} \in C(\Theta)$.

(H_7) There exist $\bar{M} : C(\Theta) \times C(\Theta) \rightarrow \mathbb{R}_+^*$ and $\bar{N} : \Theta \rightarrow (0, 1)$ such that for each $\chi, \mathfrak{S}, \chi_1, \mathfrak{S}_1 \in C(\Theta)$ and $\theta \in \Theta$

$$|\Psi(\theta, \chi, \mathfrak{S}) - \Psi(\theta, \chi_1, \mathfrak{S}_1)| \leq \bar{M}(\chi, \mathfrak{S}) \|\chi - \mathfrak{S}\|_\infty + \bar{N}(\theta) \|\chi_1 - \mathfrak{S}_1\|_\infty$$

with

$$\left\| \varsigma + \frac{1}{\alpha} e^{-\frac{\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \frac{\bar{M}(\chi, \mathfrak{S})}{1 - \bar{N}^*} d\tau \right\|_\infty^2 \leq \psi(\|\chi - \mathfrak{S}\|_\infty^2).$$

(H₈) There exist $\psi \in \tilde{\Xi}$ and $\bar{\lambda}_0 \in C(\Theta)$ and a function $\gamma_3 : C(\Theta) \times C(\Theta) \rightarrow \mathbb{R}$, such that

$$\gamma_3 \left(\bar{\lambda}_0(\theta), -\bar{\psi}(\bar{\lambda}_0) + e^{\frac{-\beta}{\alpha}\theta} + \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi(\tau) d\tau \right) \geq 0$$

where $\Phi \in C(\Theta)$ such that $\Phi(\theta) = \Psi(\theta, \bar{\lambda}_0(\theta), \Phi(\theta))$.

(H₉) For each $\theta \in \Theta$, and $\chi, \mathfrak{S} \in C(\Theta)$, we have:

$$\gamma_3(\chi(\theta), \mathfrak{S}(\theta)) \geq 0$$

implies

$$\begin{aligned} & \gamma_3 \left(-\bar{\psi}(\chi) + \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi(\tau) d\tau, -\bar{\psi}(\mathfrak{S}) \right. \\ & \left. + \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi'(\tau) d\tau \right) \geq 0, \end{aligned}$$

where $\Phi, \Phi' \in C(\Theta)$ such that

$$\Phi(\theta) = \Psi(\theta, \chi(\theta), \Phi(\theta))$$

and

$$\Phi'(\theta) = \Psi(\theta, \mathfrak{S}(\theta), \Phi'(\theta)).$$

Theorem 4.1. *Assume that the hypotheses (H₄) and (H₆)-(H₉) hold. Then the problem (3) has at least one solution. And, if (H₅) holds, then the solution is unique.*

Proof. Let $\mathcal{K}' : C(\Theta) \rightarrow C(\Theta)$ be the operator given by:

$$(\mathcal{K}'\chi)(\theta) = (\chi_0 - \bar{\psi}(\chi))e^{\frac{-\beta}{\alpha}\theta} + \frac{1}{\alpha} e^{\frac{-\beta}{\alpha}\theta} \int_0^\theta e^{\frac{\beta}{\alpha}\tau} \Phi(\tau) d\tau, \quad (10)$$

where $\Phi \in C(\Theta)$ such that $\Phi(\theta) = \Psi(\theta, \chi(\theta), \Phi(\theta))$.

Clearly, the fixed points of the operator \mathcal{K}' are solution of the problem (3). By repeating the same process of Theorem 3.2, we can easily show all the conditions of Theorem 4.1 are satisfied by \mathcal{K}' . \square

5 An Example

Consider the following problem which is an example of our problem (1)-(2):

$$\begin{cases} \left(\mathfrak{D}_0^{\frac{1}{2}} \xi \right) (\theta) = \frac{1 + \sin(|\xi(\theta)|)}{4(1 + |\xi(\theta)|)} + \frac{1}{4(1 + |\left(\mathfrak{D}_0^{\frac{1}{2}} \xi \right)(\theta)|)}, \\ \xi(0) = 0. \end{cases} \quad (11)$$

Set

$$\Psi(\theta, \xi, \mathfrak{S}) = \frac{1 + \sin(|\xi|)}{4(1 + |\xi|)} + \frac{1}{4(1 + |\mathfrak{S}|)},$$

where $\theta \in \Theta := [0, 1]$, $\xi, \mathfrak{S} \in \mathbb{R}$.

Let $(C(\Theta), \delta, 2)$ be the complete b-metric space with $\varepsilon = 2$, such that $\delta : C(\Theta) \times C(\Theta) \rightarrow \mathbb{R}_+$, is defined by:

$$\delta(\xi, \mathfrak{S}) = \|(\xi - \mathfrak{S})^2\|_\infty := \sup_{\theta \in \Theta} |\xi(\theta) - \mathfrak{S}(\theta)|^2.$$

For any $\xi, \bar{\xi} \in C(\Theta)$, $\mathfrak{S}, \bar{\mathfrak{S}} \in \mathbb{R}$ and $\theta \in \Theta$. If $|\xi(\theta)| \leq |\mathfrak{S}(\theta)|$, then

$$\begin{aligned} & |\Psi(\theta, \xi, \bar{\xi}) - \Psi(\theta, \mathfrak{S}, \bar{\mathfrak{S}})| \\ & \leq \left| \frac{1 + \sin(|\xi(\theta)|)}{4(1 + |\xi(\theta)| + |\bar{\xi}(\theta)|)} - \frac{1 + \sin(|\mathfrak{S}(\theta)|)}{4(1 + |\mathfrak{S}(\theta)| + |\bar{\mathfrak{S}}(\theta)|)} \right| \\ & \quad + \frac{|\bar{\xi}(\theta) - \bar{\mathfrak{S}}(\theta)|}{4}, \\ & \leq \frac{1}{4} ||\xi(\theta)| - |\mathfrak{S}(\theta)|| + \frac{1}{4} |\sin(|\xi(\theta)|) - \sin(|\mathfrak{S}(\theta)|)| \\ & \quad + ||\xi(\theta)| \sin(|\mathfrak{S}(\theta)|) - |\mathfrak{S}(\theta)| \sin(|\xi(\theta)|)| \\ & \quad + \frac{|\bar{\xi}(\theta) - \bar{\mathfrak{S}}(\theta)|}{4} \\ & \leq |\xi(\theta) - \mathfrak{S}(\theta)| + \frac{1}{4} |\sin(|\xi(\theta)|) - \sin(|\mathfrak{S}(\theta)|)| \\ & \quad + \frac{|\bar{\xi}(\theta) - \bar{\mathfrak{S}}(\theta)|}{4} \\ & \quad + ||\mathfrak{S}(\theta)| \sin(|\mathfrak{S}(\theta)|) - |\mathfrak{S}(\theta)| \sin(|\xi(\theta)|)| \\ & = |\xi(\theta) - \mathfrak{S}(\theta)| + (1 + |\mathfrak{S}(\theta)|) |\sin(|\xi(\theta)|) - \sin(|\mathfrak{S}(\theta)|)| \end{aligned}$$

$$\begin{aligned}
 & + \frac{|\bar{\xi}(\theta) - \bar{\mathfrak{S}}(\theta)|}{4} \\
 & \leq |\xi(\theta) - \mathfrak{S}(\theta)| + \frac{1}{2}(1 + |\mathfrak{S}(\theta)|) \\
 & \quad \times \left| \sin \left(\frac{||\xi(\theta)| - |\mathfrak{S}(\theta)||}{2} \right) \right| \left| \cos \left(\frac{|\xi(\theta)| + |\mathfrak{S}(\theta)|}{2} \right) \right| \\
 & \leq (2 + \|\mathfrak{S}\|_\infty) \|\xi - \mathfrak{S}\|_\infty + \frac{\|\bar{\xi} - \bar{\mathfrak{S}}\|_\infty}{4}.
 \end{aligned}$$

The case when $|\mathfrak{S}(\theta)| \leq |\xi(\theta)|$, we get

$$|\Psi(\theta, \xi, \bar{\xi}) - \Psi(\theta, \mathfrak{S}, \bar{\mathfrak{S}})| \leq (2 + \|\xi\|_\infty) \|\xi - \mathfrak{S}\|_\infty + \frac{\|\bar{\xi} - \bar{\mathfrak{S}}\|_\infty}{4}.$$

Hence

$$|\Psi(\theta, \xi, \bar{\xi}) - \Psi(\theta, \mathfrak{S}, \bar{\mathfrak{S}})| \leq \min\{2 + \|\xi\|_\infty, 2 + \|\mathfrak{S}\|_\infty\} \|\xi - \mathfrak{S}\|_\infty + \frac{\|\bar{\xi} - \bar{\mathfrak{S}}\|_\infty}{4},$$

Thus, hypothesis (H_1) is satisfied with

$$\gamma_1(\xi, \mathfrak{S}) = \min\{2 + \|\xi\|_\infty, 2 + \|\mathfrak{S}\|_\infty\}$$

and

$$\gamma_2(\theta) = \frac{1}{4}.$$

Let $\lambda(\theta) = \frac{1}{8}\theta$, $\phi(\theta) = \theta$, $\varpi : C(\Theta) \times C(\Theta) \rightarrow \mathbb{R}_+^*$ with

$$\begin{cases} \varpi(\xi, \mathfrak{S}) = 1; & \text{if } \delta(\xi(\theta), \mathfrak{S}(\theta)) \geq 0, \theta \in \Theta, \\ \varpi(\xi, \mathfrak{S}) = 0; & \text{else,} \end{cases}$$

and $\delta : C(\Theta) \times C(\Theta) \rightarrow \mathbb{R}$ with $\delta(\xi, \mathfrak{S}) = \|\xi - \mathfrak{S}\|_\infty$.

Hypothesis (H_2) is satisfied with $\bar{\mu}_0(\theta) = \xi_0$. Also, (H_3) holds from the definition of the function δ . Since all requirements of Theorem 3.2 are verified, then we conclude the existence and the uniqueness of solutions for problem (11).

References

- [1] S. Abbas, M. Benchohra, J.R. Graef and J. Henderson, *Implicit Fractional Differential and Integral Equations: Existence and Stability*, De Gruyter, Berlin, 2018.
- [2] S. Abbas, M. Benchohra and G. M. N'Guérékata, *Topics in Fractional Differential Equations*, Springer, New York, 2012.
- [3] S. Abbas, M. Benchohra and G. M. N'Guérékata, *Advanced Fractional Differential and Integral Equations*, Nova Science Publishers, New York, 2015.
- [4] T. Abdeljawad, On conformable fractional calculus. *J. Comput. Appl. Math.* **279** (2015), 57-66.
- [5] H. Afshari, H. Aydi, E. Karapinar, On generalized $\varpi - \psi$ -Geraghty contractions on b -metric spaces, *Georgian Math. J.* **27**(1) (2020), 9-21.
- [6] B. Alqahtani, A. Fulga, F. Jarad and E. Karapinar, Nonlinear F -contractions on b -metric spaces and differential equations in the frame of fractional derivatives with Mittag-Leffler kernel, *Chaos, Solitons & Fractals.* **128** (2019), 349-354.
- [7] M. Benchohra, F. Bouazzaoui, E. Karapinar and A. Salim, Controllability of second order functional random differential equations with delay. *Mathematics* **10** (2022), 16pp. <https://doi.org/10.3390/math10071120>
- [8] N. Benkhetto, K. Aissani, A. Salim, M. Benchohra and C. Tunc, Controllability of fractional integro-differential equations with infinite delay and non-instantaneous impulses, *Appl. Anal. Optim.* **6** (2022), 79-94.
- [9] S. Cobzas and S. Czerwik. The completion of generalized b -metric spaces and fixed points, *Fixed Point Theory* **21** (1) (2020), 133-150.
- [10] S. Czerwik, Nonlinear set-valued contraction mappings in b -metric spaces, *Atti Semin. Mat. Fis. Univ. Modena.* **46** (2) 1998, 263-276.

- [11] S. Czerwik, Contraction mappings in b -metric spaces, *Acta Math. Inf. Univ. Ostrav.* **1** (1993), 5-11.
- [12] C. Derbazi, H. Hammouche, A. Salim and M. Benchohra, Measure of noncompactness and fractional hybrid differential equations with hybrid conditions. *Differ. Equ. Appl.* **14** (2022), 145-161. <http://dx.doi.org/10.7153/dea-2022-14-09>
- [13] A. Heris, A. Salim, M. Benchohra and E. Karapinar, Fractional partial random differential equations with infinite delay. *Results in Physics.* (2022). <https://doi.org/10.1016/j.rinp.2022.105557>
- [14] S. Krim, S. Abbas, M. Benchohra and E. Karapinar, Terminal value problem for implicit Katugampola fractional differential equations in b -metric spaces, *J. Funct. Spaces* **2021** (2021), 7 pp.
- [15] N. Laledj, A. Salim, J. E. Lazreg, S. Abbas, B. Ahmad and M. Benchohra, On implicit fractional q -difference equations: Analysis and stability. *Math. Methods Appl. Sci.* **45** (2022), 10775-10797. <https://doi.org/10.1002/mma.8417>
- [16] M. Mebrat, G. N'Guérékata, A Cauchy problem for some fractional differential equation via deformable derivatives, *J. Nonlinear Evol. Equ. Appl.* **2020** (2020), 55-63.
- [17] M. Mebrat, G. N'Guérékata, An existence result for some fractional-integro differential equations in Banach spaces via deformable derivative, *J. Math. Ext.* **16** (2022), 1-19.
- [18] A. Meraj, D. N Pandey, Existence and uniqueness of mild solution and approximate controllability of fractional evolution equations with deformable fractional derivative, *J. Nonlinear Evol. Equ. Appl.* **2018** (2019), 85-100.
- [19] A. Salim, S. Abbas, M. Benchohra and E. Karapinar, Global stability results for Volterra-Hadamard random partial fractional integral equations. *Rend. Circ. Mat. Palermo (2)*. (2022), 1-13. <https://doi.org/10.1007/s12215-022-00770-7>

- [20] A. Salim, M. Benchohra, J. R. Graef and J. E. Lazreg, Initial value problem for hybrid ψ -Hilfer fractional implicit differential equations. *J. Fixed Point Theory Appl.* **24** (2022), 14 pp. <https://doi.org/10.1007/s11784-021-00920-x>
- [21] A. Salim, J. E. Lazreg, B. Ahmad, M. Benchohra and J. J. Nieto, A study on k -generalized ψ -Hilfer derivative operator, *Vietnam J. Math.* (2022). <https://doi.org/10.1007/s10013-022-00561-8>
- [22] S. G. Samko, A. A. Kilbas and O. I. Marichev, *Fractional Integrals and Derivatives. Theory and Applications*, Gordon and Breach, Amsterdam, 1987, Engl. Trans. from the Russian.
- [23] V. E. Tarasov, *Fractional Dynamics: Application of Fractional Calculus to Dynamics of Particles, Fields and Media*, Springer, Heidelberg; Higher Education Press, Beijing, 2010.
- [24] Y. Zhou, *Basic Theory of Fractional Differential Equations*, World Scientific, Singapore, 2014.
- [25] F. Zulfeqarr, A. Ujlayan, P. Ahuja, A new fractional derivative and its fractional integral with some applications, 2017, arXiv: 1705.00962v1, 11 pages.

Abdelkrim Salim

Faculty of Technology, Hassiba Benbouali University of Chlef
Assistant Professor of Mathematics
P.O. Box 151 Chlef 02000, Algeria
E-mail: salim.abdelkrim@yahoo.com, a.salim@univ-chlef.dz

Salim Krim

Laboratory of Mathematics, Djillali Liabes University of Sidi Bel-Abbes
P.O. Box 89, Sidi Bel-Abbes 22000, Algeria
E-mail: salimsalimkrim@gmail.com

Saïd Abbas

Department of Electronics, University of Saïda-Dr. Moulay Tahar
Professor of Mathematics
P.O. Box 138, EN-Nasr, 20000 Saïda, Algeria

ON DEFORMABLE IMPLICIT FRACTIONAL DIFFERENTIAL
EQUATIONS IN b -METRIC SPACES

17

E-mail: abbasmsaid@yahoo.fr, said.abbas@univ-saida.dz

Mouffak Benchohra

Laboratory of Mathematics, Djillali Liabes University of Sidi Bel-Abbes

Assistant Professor of Mathematics

P.O. Box 89, Sidi Bel-Abbes 22000, Algeria

E-mail: benchohra@yahoo.com